## Orientations of graphs

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#### Orientation

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#### root-connected, strongly connected orientation

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#### 2-arc-connected orientation

Being proud of himself, he presents his project to his assistant, a well-balanced man, who reminds him that during summer, some streets of the city may be blocked by floods, they thus try to conceive a plan where blocking any street does not make a district inaccessible.

#### well-balanced orientation

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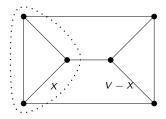
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- strongly connected / k-arc-connected
- well-balanced
- k-connected

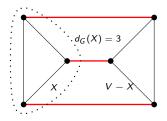
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#### • same problems with prescribed degrees

- Given an undirected graph G,
  - $d_G(X)$  = number of edges of G entering X,
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- Given a directed graph D,
  - $d_D^-(X) =$  number of arcs of D entering X
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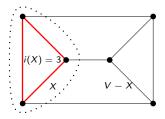
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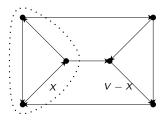
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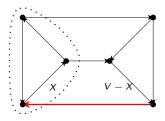


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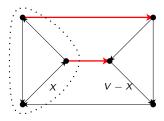
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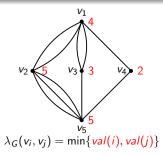


## Definitions

- local-edge-connectivity  $\lambda_G(u, v) = \text{maximum number of edge-disjoint}$ paths from u to v in G,
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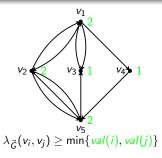
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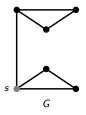
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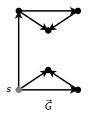
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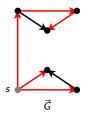
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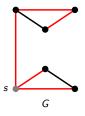
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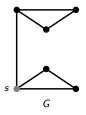
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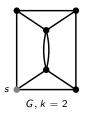
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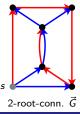
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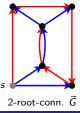
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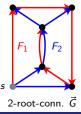
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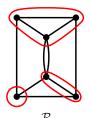
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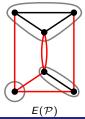
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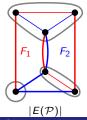
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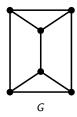


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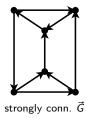
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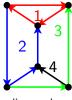
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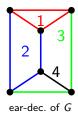


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# Theorem (Nash-Williams'60)(weak orientation)

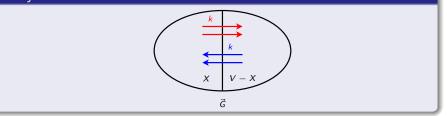
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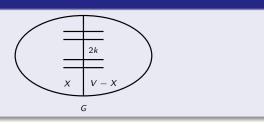
#### necessity :



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#### sufficiency :

- G' is minimally 2k-edge-connected,
- there exists a vertex of degree 2k,
- there exists a 2k-admissible complete splitting off,  $\implies$  (induction)
- there exists a k-arc-connected orientation  $\vec{G}''$  of G'',  $\Longrightarrow$
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G 2k-e-c.

Z. Szigeti (G-SCOP, Grenoble)

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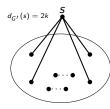
Orientations of graphs

8 November 2011 14 / 31

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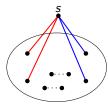
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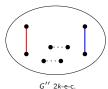


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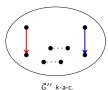
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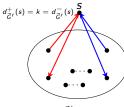
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 $\vec{G}'$  k-a-c.

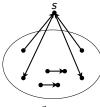
Z. Szigeti (G-SCOP, Grenoble)

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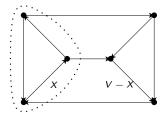
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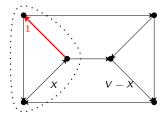
• If *m* is the in-degree vector of  $D(m(v) = d_D^-(v) \forall v \in V)$ , then  $m(X) - i_D(X) = d_D^-(X).$ 

• The in-degree vector characterizes the in-degree function.



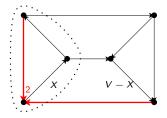
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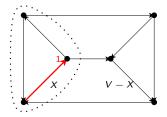
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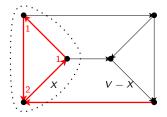
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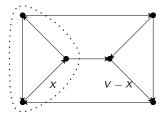
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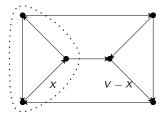
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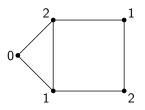
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Given an undirected graph G = (V, E) and a vector  $m: V \to \mathbb{Z}_+$ ,

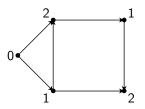
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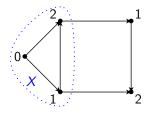
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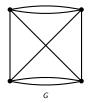
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## Applications

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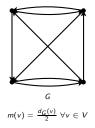
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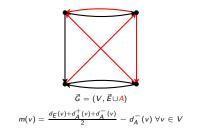
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 $G = (V, E \cup A)$ 

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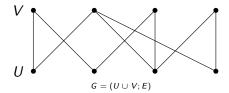


Z. Szigeti (G-SCOP, Grenoble)

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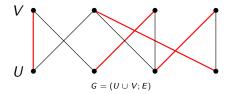
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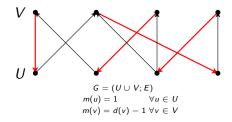
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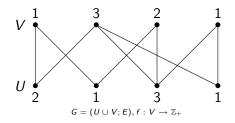
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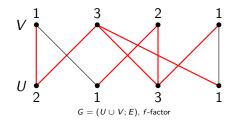
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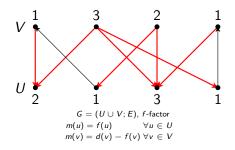
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### Theorem (Frank'80)

Given an undirected graph G = (V, E) and a vector  $m: V \to \mathbb{Z}_+$ , there exists an orientation  $\vec{G}$  of G with in-degree vector m that is  $\iff$ 

- root-connected :
- k-root-connected :
- strongly connected :
- k-arc-connected :

 $d_{\vec{G}}^{-}(X) \ge 1 \ \forall X \subset V - s, \ s \ fixed,$  $d_{\vec{G}}^{-}(X) \ge k \ \forall X \subset V - s, \ s \ fixed,$  $d_{\vec{G}}^{-}(X) \ge 1 \ \forall X \subset V,$  $d_{\vec{G}}^{-}(X) \ge k \ \forall X \subset V,$  $d_{\vec{G}}^{-}(V) = 0.$ 

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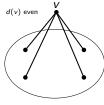
m(V)-|E|=0.

## Eulerian orientation

#### Exercise

#### • Let G be an Eulerian graph.

2 Let G be an Eulerian graph and P<sub>v</sub> a partition of the edges incident to v into pairs for every v ∈ V.

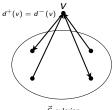


G eulerian

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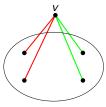
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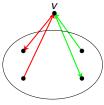
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G eulerian,  $\mathcal{P}_{v}$  partition

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 $\vec{G}$  eulerian and compatible with  $\mathcal{P}_v$ 

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An orientation  $\vec{G}$  of an Eulerian graph G is Eulerian  $\iff$ 

- $d_{\vec{c}}^{-}(X) d_{\vec{c}}^{+}(X) = 0 \quad \forall X \subseteq V$
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• Let G be an Eulerian graph. Then G has an Eulerian orientation  $\vec{G}$ .

2 Let G be an Eulerian graph and P<sub>v</sub> a partition of the edges incident to v into pairs for every v ∈ V. Then G has an Eulerian orientation G that is compatible with each P<sub>v</sub>.

### Exercise

An orientation  $\vec{G}$  of an Eulerian graph G is Eulerian  $\iff$ 

- $d_{\vec{G}}^{-}(v) d_{\vec{G}}^{+}(v) = 0 \quad \forall v \in V \qquad \Longleftrightarrow$  $d_{\vec{G}}^{-}(X) - d_{\vec{G}}^{+}(X) = 0 \quad \forall X \subseteq V \qquad \Longleftrightarrow$
- $\begin{array}{ll} & d^-_{\vec{G}}(X) d^+_{\vec{G}}(X) = 0 & \forall X \subseteq V \\ \\ & \mathbf{3} & d^-_{\vec{C}}(X) = \frac{1}{2}d_G(X) & \forall X \subseteq V \end{array}$
- $\lambda_{\vec{G}}(u,v) = \frac{1}{2}\lambda_{G}(u,v) \ \forall (u,v) \in V \times V.$

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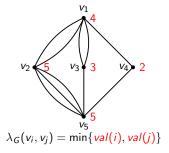
 $\Longrightarrow$ 

## Definition

An orientation  $\vec{G}$  of a graph G is best-balanced if

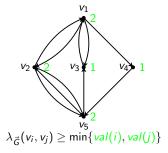
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$$\lfloor \frac{1}{2} \lambda_G(u, v) \rfloor$$
  $\forall (u, v) \in V \times V$ , (well-balanced)
 A<sub>G</sub><sup>-</sup>(v) - d<sup>+</sup><sub>G</sub>(v) | ≤ 1  $\forall v \in V$ . (smooth)

## Theorem (Nash-Williams'60)(strong orientation)

Every graph G admits a best-balanced orientation.

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$$\begin{array}{l} \bullet \quad \lambda_{\vec{G}}(u,v) \geq \lfloor \frac{1}{2}\lambda_{G}(u,v) \rfloor \quad \forall (u,v) \in V \times V, \text{ (well-balanced)} \\ \bullet \quad |d_{\vec{G}}^{-}(v) - d_{\vec{G}}^{+}(v)| \leq 1 \quad \forall v \in V. \quad \text{(smooth)} \end{array}$$

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#### strong orientation implies weak orientation

• G is 2k-edge-connected

 $\lambda_G(u,v) \geq 2k \; orall(u,v) \in V imes V \Longrightarrow ( ext{strong orient.})$ 

- there exists  $\vec{G}: \lambda_{\vec{G}}(u,v) \geq k \quad \forall (u,v) \in V \times V \Longrightarrow$
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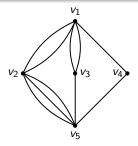
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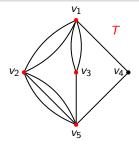
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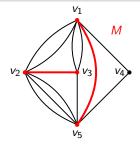
- **①** Take the set  $T_G$  of odd degree vertices of G,
- ② add a pairing M of  $T_G : G + M$  is Eulerian,
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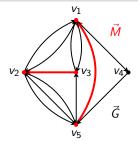
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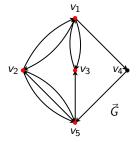
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#### Exercise : How to find a smooth orientation?

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There exists a pairing M of  $T_G$  and there exists an Eulerian orientation  $\vec{G} + \vec{M}$  of G + M such that  $\vec{G}$  is well-balanced.

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### Theorem (Nash-Williams'60)(pairing theorem)

There exists a pairing M of  $T_G$  such that for every Eulerian orientation  $\vec{G} + \vec{M}$  of G + M,  $\vec{G}$  is well-balanced.

For every subgraph H of a graph G, there exists an orientation  $\vec{G}$  of G :  $\vec{G}$  and  $\vec{G}(H)$  are best-balanced orientations of G and H.

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Easy by pairing theorem.

Z. Szigeti (G-SCOP, Grenoble)

$$\mathbf{P}_{\mathbf{G}}^{k} := \{ m : \mathbb{R}^{V} : m(X) \ge i_{\mathbf{G}}(X) + k \ \forall X \subset V, m(V) = |\mathbf{E}| \}.$$

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- Minimum Cost k-Arc-Connected Orientation Problem can be solved in polynomial time.

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- Minimum Cost Well-Balanced Orientation Problem is NP-complete.

# k-connected graphs

#### Definition

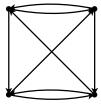
A directed graph D = (V, A) with |V| > k is *k*-connected D - X is strongly connected for all  $X \subset V$  with |X| = k - 1

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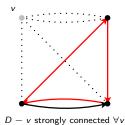


D 2-connected

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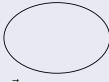
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## Conjecture [Frank]

- Given an undirected graph G = (V, E) with |V| > k,
  - there exists a k-connected orientation of G

- $\Leftarrow$
- G X is (2k 2|X|)-edge-connected for all  $X \subseteq V$  with |X| < k.

#### necessity :



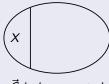
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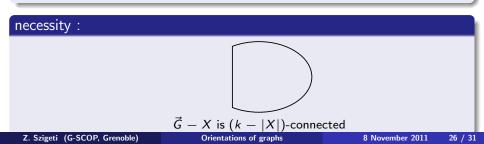
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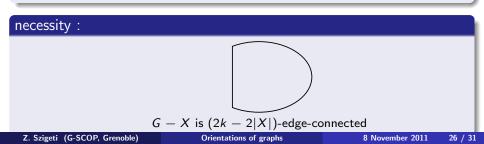
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# Conjecture [Frank]

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## Theorem (Berg-Jordán'06)

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# Conjecture [Frank]

Given an undirected graph G = (V, E) with |V| > 2,

- there exists a 2-connected orientation of G
- G is 4-edge-connected and G v is 2-edge-connected for all  $v \in V$ .

## Theorem (Berg-Jordán'06)

Given an Eulerian graph G = (V, E) with |V| > 2,

- there exists a 2-connected Eulerian orientation of G
- G is 4-edge-connected and G v is 2-edge-connected for all  $v \in V$ .

Given an Eulerian graph G = (V, E) with |V| > 2,

- there is an Eulerian  $\vec{G}$  of G s. t.  $\vec{G} v$  is 1-arc-conn.  $\forall v \in V \iff$
- G v is 2-edge-connected for all  $v \in V$ .

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## Theorem (Király-Szigeti'06)

Given an Eulerian graph G = (V, E) with |V| > k + 1,

- there is an Eulerian  $\vec{G}$  of G s. t.  $\vec{G} v$  is k-arc-conn.  $\forall v \in V \iff$
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- very short, applying pairing theorem,
  - provides a short proof for Berg-Jordán's theorem.

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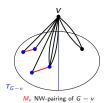
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#### sufficiency :

## • Let $M_v$ be a NW-pairing for G - v for each $v \in V$ .

- $M_v$  provides pairs of edges incident to v,
- Let  $\vec{G}$  be an Eulerian orientation of G compatible with each  $\mathcal{P}_{v}$ .
- $\vec{G}$  provides an orientation  $\vec{M}_v$  of  $M_v$ .
- $\vec{G} v + \vec{M}_v$  is Eulerian,



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Orientations of graphs

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#### sufficiency :

- Let  $M_v$  be a NW-pairing for G v for each  $v \in V$ .
- *M<sub>v</sub>* provides pairs of edges incident to *v*, the remaining edges has a natural partition into pairs, let *P<sub>v</sub>* be the partition obtained.
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- Let  $\vec{G}$  be an Eulerian orientation of G compatible with each  $\mathcal{P}_{v}$ .
- $\vec{G}$  provides an orientation  $\vec{M}_v$  of  $M_v$ .
- $\vec{G} v + \vec{M}_v$  is Eulerian,  $(G v \text{ is } 2k\text{-edge-connected} \text{ and } M_v \text{ is a } NW\text{-pairing for } G v)$  so  $\vec{G} v$  is k-arc-connected for each  $v \in V$ .



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## Theorem (Cheriyan-Durand de Gevigney-Szigeti'11)

Every 14-connected graph has a 2-connected orientation, that is  $f(2) \leq 14$ .

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Every 14-connected graph has a 2-connected orientation, that is  $f(2) \leq 14$ .

Frank's conjecture would imply that  $f(2) \leq 4$ .

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## Theorem (Cheriyan-Durand de Gevigney-Szigeti'11)

Every (12k + 2)-connected graph has an orientation  $\vec{G}$  such that  $\vec{G} - v$  is k-arc-connected  $\forall v \in V$ .

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