Old and new results on packing arborescences in directed hypergraphs

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Abstract

We propose a further development in the theory of packing arborescences. First we review some of the existing results on packing arborescences and then we provide common generalizations of them to directed hypergraphs. We introduce and solve the problem of reachability-based packing of matroid-rooted hyperarborescences and we also solve the minimum cost version of this problem. Furthermore, we introduce and solve the problem of matroid-based packing of matroid-rooted mixed hyperarborescences.

Keywords: Arborescence, Packing, Directed Hypergraph, Matroid

1. Introduction

We study packings of arborescences in this paper. An $r$-arborescence is a directed tree on a vertex-set containing the root vertex $r$ in which each vertex has in-degree 1 except $r$. Throughout this paper, by packing subgraphs in a directed (hyper)graph, we mean a set of arc-disjoint subgraphs. (For other definitions, see the next section.) The starting point of the research on arborescence-packings is the following famous result of Edmonds [6] on packing spanning arborescences.

\textbf{Theorem 1} ([6]). \textit{There exists a packing of $k$ spanning $r$-arborescences in a digraph $\vec{G} = (V, A)$ if and only if}

\begin{equation}
\varrho_{A}(X) \geq k \quad \text{for all } \emptyset \neq X \subseteq V \setminus r \text{ where } \varrho_{A}(X) \text{ denotes the in-degree of } X.
\end{equation}

This result has extensions in many directions. For our purposes let us mention four of them: the result of Kamiyama, Katoh, Takizawa [13] on packing reachability arborescences (Theorem 4 in this paper), Theorem 5 on packing matroid-rooted arborescences with matroid constraint by Durand de Gevigney, Nguyen, Szigeti [5], Theorem 3 on packing spanning hyperarborescences (Frank, T. Király, Z. Király [10]) and Theorem 7 on packing spanning mixed arborescences (Frank [9]). Figure 1 shows all possible combinations of these extensions. The results without citations corresponding to black boxes of the diagram are presented in this paper, the ones in gray are yet to be proved to be in P (see Section 7.1).

The main contribution of this work is to show how the existing hypergraphical results can be derived directly from their graphical counterparts. We note that the original proofs of these results were different. Both Frank, Z. Király and T. Király [10] and Bérczi and Frank [2] showed that a directed hypergraph satisfying their condition for the packing problem can be reduced – by an operation called \textit{trimming} – to a digraph satisfying the condition of the graphical counterpart of their problem.

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Figure 1: All possible common generalizations of the 4 problems mentioned in the introduction.

Our method looks a bit similar to this; however, we also add some extra vertices to the digraph to ensure that the condition of the graphical result holds automatically for the digraph if the hypergraphical condition holds for the directed hypergraph. We also note that this method allows us to find a minimum cost solution of these problems for any cost function on the set of directed hyperedges.

Using the same method, we solve the problem of reachability-based packing of matroid-rooted hyperarborescences, that is, a common generalization of three of the above four extensions, excluding the mixed one. We also consider a generalization of other three of the above four extensions, excluding the reachability one this time, namely the problem of matroid-based packing of matroid-rooted mixed hyperarborescences. Using a new orientation result (Theorem 11) on hypergraphs covering intersecting supermodular functions, we reduce this problem to its directed version, the problem of matroid-based packing of matroid-rooted hyperarborescences, which in turn is a special case of the problem of reachability-based packing of matroid-rooted hyperarborescences.

2. Definitions

In this paper, \( H = (V, E) \) will be a hypergraph. We assume that all the hyperedges in \( E \) are of size at least 2. When all the hyperedges are of size 2, that is, when the hypergraph is a graph, we will denote it by \( G = (V, E) \). For a vertex set \( X \), \( i_E(X) \) denotes the number of hyperedges in \( E \) that are contained in \( X \). For a partition \( P = \{V_0, V_1, \ldots, V_\ell\} \) of \( V \), where only \( V_0 \) can be empty, we denote by \( e_E(P) \) the number of hyperedges in \( E \) intersecting at least two members of \( P \).

Let \( \vec{H} = (V, A) \) be a directed hypergraph (dypergraph for short) where \( V \) denotes the set of vertices and \( A \) denotes the set of dyperedges of \( \vec{H} \). By a dyperedge we mean a pair \( (Z, z) \) such that \( z \in Z \subseteq V \), where \( z \) is the head of the dyperedge \( (Z, z) \) and the elements of \( Z \setminus z \) are the tails of the dyperedge \( (Z, z) \). We assume that each dyperedge has one head and at least one tail. When a dypergraph is a digraph, we will denote it by \( \vec{G} = (V, A) \). Let \( X \subseteq V \). We say that the dyperedge \( (Z, z) \) enters \( X \) if the head of
(Z, z) is in X and at least one tail of (Z, z) is not in X. We define the in-degree $g_A(X)$ of X as the number of dyperedges in A entering X.

For a set function h on V, we say that the dypergraph $\mathcal{H}$ covers h if

$$g_A(X) \geq h(X) \text{ for all } X \subseteq V. \quad (2)$$

By trimming the dypergraph $\mathcal{H}$ we mean replacing each dyperedge $(Z, z)$ of $\mathcal{H}$ by an arc tz where t is one of the tails of the dyperedge $(Z, z)$.

By an orientation of $\mathcal{H}$, we mean a dypergraph $\mathcal{H}$ obtained from $\mathcal{H}$ by choosing, for every $Z \in \mathcal{E}$, an orientation of $Z$, that is by choosing a head $z$ for $Z$.

Let $p$ be a set function on V. We call $p$ supermodular if for every $X, Y \subseteq V$,

$$p(X) + p(Y) \leq p(X \cap Y) + p(X \cup Y). \quad (3)$$

We say that $p$ is intersecting supermodular if (3) is satisfied for every $X, Y \subseteq V$ when $X \cap Y \neq \emptyset$. A set function $b$ is called submodular if $-b$ is supermodular. It is well known that $i_{\mathcal{E}}$ is supermodular and that $g_A$ is submodular (see e.g. in [8]).

In a dypergraph $\mathcal{H} = (V, A)$, we say that a vertex $w$ can be reached from a vertex $u$ if there exists an alternating sequence $v_1 = u, Z_1, v_2, \ldots, v_i, Z_i, v_{i+1}, \ldots, v_j = w$ of vertices and dyperedges such that $v_i$ is a tail of $Z_i$ and $v_{i+1}$ is the head of $Z_i$. For a set $X \subseteq V$, we denote by $P_A(X)$ the set of vertices from which $X$ can be reached in $\mathcal{H}$ and by $Q_A(X)$ the set of vertices that can be reached from $X$ in $\mathcal{H}$. We call the pair $(\mathcal{H}, \mathcal{E})$ a rooted dypergraph. For $X \subseteq V$, we define $p^{\mathcal{R}}(X)$ as the number of members of $\mathcal{R}$ disjoint from $X$ and $q_A^\mathcal{R}(X)$ as the number of members of $\mathcal{R}$’s which do not intersect $X$ but from which $X$ is reachable in $\mathcal{H}$, in other words: $q_A^\mathcal{R}(X) = \{|i : R_i \cap X = \emptyset, Q_A(R_i) \cap X \neq \emptyset\}$. When each $R_i$ consists of a single vertex $r_i$, we denote $\mathcal{R}$ by $R$.

For a non-empty set $R \subseteq U$, a subdigraph of $\vec{G} = (V, A)$ is called an R-branching if it consists of $|R|$ vertex-disjoint arborescences whose roots are in $R$. The results of Frank, Z. Király and T. Király [10] and Bérczi and Frank [2] inspire us to extend the definition of arborescences and branchings to dypergraphs, as follows. Let $\vec{T} = (U, A')$ be a subdypergraph of $\mathcal{H} = (V, A)$ such that $U$ is the vertex set spanned by $A'$ and $R \subseteq U$. Let $U'$ be the set of vertices in $U$ whose in-degree in $\vec{T}$ is not 0. We say that $\vec{T}$ is an R-hyperbranching if it can be trimmed to an R-branching with vertex-set $U' \cup R$. (It is easy to see that this is equivalent to the following: $R \subseteq U, g_A'(r) = 0$ for all $r \in R, g_A'(u) = 1$ for all $u \in U'$, $g_A'(X) \geq 1$ for all $X \subseteq V \setminus R, X \cap U' \neq \emptyset$.) When $R = \{r\}$, an R-hyperbranching is also called an $r$-hyperarborescence.

Remark 1. R-hyperbranchings and R-branchings coincide for digraphs, and our subsequent definitions for hypergraphs are also straightforward generalizations of the original definitions for graphs. Therefore, we will define everything only for the general hypergraphical case.

We call $\vec{T}$ a reachability R-hyperbranching in $\mathcal{H}$ if $U' \cup R$ contains the set $Q_A(R)$, in other words, if $Q_A(\vec{T}) = Q_A(R)$. If all the vertices can be reached from $R$ in $\mathcal{H}$, then a reachability R-hyperbranching is called spanning. In a rooted dypergraph $(\mathcal{H}, \mathcal{E} = \{R_1, \ldots, R_k\})$, a set of arc-disjoint spanning (reachability, resp.) hyperbranchings is called a packing of spanning (reachability, resp.) R-hyperbranchings. Examples of a spanning hyperarborescence and of a reachability hyperarborescence can be found in Figure 2.
A matroid-rooted hyperarborescence is a triple \((\mathcal{T}, r, s)\) where \(\mathcal{T}\) is a \(r\)-hyperarborescence and \(s\) is an element of \(S\) mapped to \(r\). We say that \(s\) is the matroid-root of the matroid-rooted hyperarborescence \((\mathcal{T}, r, s)\). A matroid-based packing of matroid-rooted hyperarborescences in \((\overline{\mathcal{H}}, \mathcal{M}, S, \pi)\) is a set \(\{(\mathcal{T}_1, r_1, s_1), \ldots, (\mathcal{T}_{|S|}, r_{|S|}, s_{|S|})\}\) of pairwise dyperedge-disjoint matroid-rooted hyperarborescences such that for each \(v \in V\), the set \(\mathcal{B}_v\) of matroid-roots of the matroid-rooted hyperarborescences in which the vertex \(v\) can be reached from their roots forms a base of the matroid \(\mathcal{M}\), that is \(\mathcal{B}_v = \{s_i \in S : v \in Q_{\mathcal{M}}(\mathcal{T}_i)\}\) is a base of \(S\). A reachability-based packing of matroid-rooted hyperarborescences in \((\overline{\mathcal{H}}, \mathcal{M}, S, \pi)\) is a set \(\{(\mathcal{T}_1, r_1, s_1), \ldots, (\mathcal{T}_{|S|}, r_{|S|}, s_{|S|})\}\) of pairwise dyperedge-disjoint matroid-rooted hyperarborescences such that for each \(v \in V\), the set \(\mathcal{B}_v\) is a base of \(S_{\mathcal{M}}(v)\).

**Remark 2.** Let \((\overline{\mathcal{H}} = (V, \mathcal{A}), \mathcal{R} = \{R_1, \ldots, R_k\})\) be a rooted dypergraph. Let \(S_{\mathcal{R}} := \bigcup R_i\) (as a multiset), let \(\pi\) map each occurrence of \(r\) in \(S_{\mathcal{R}}\) to the vertex \(r \in V\), and let \(\mathcal{M}_{S_{\mathcal{R}}} := \mathcal{M}\) be the partition matroid on \(S_{\mathcal{R}}\) given by \(\mathcal{R}\) where a set \(P \subseteq S_{\mathcal{R}}\) is independent if and only if \(|P \cap R_i| \leq 1\) for \(i = 1, \ldots, k\). Then the problem of matroid-based (reachability-based, resp.) packing of matroid-rooted hyperarborescences in \((\overline{\mathcal{H}}, \mathcal{M}_{S_{\mathcal{R}}}, S, \pi)\) and that of packing spanning (reachability, resp.) \(R\)-hyperbranchings coincide.

Let \(\mathcal{F} = (V, \mathcal{E} \cup \mathcal{A})\) be a mixed hypergraph where \(\mathcal{E}\) is the set of hyperedges and \(\mathcal{A}\) is the set of dyperedges of \(\mathcal{F}\). The definitions of a rooted mixed hypergraph \((\mathcal{F}, \mathcal{R})\) and a matroid-rooted mixed hypergraph \((\mathcal{F}, \mathcal{M}, S, \pi)\) are similar to the previous definitions of a rooted and a matroid-rooted dypergraph, respectively. By a mixed \(r\)-hyperarborescence (mixed \(R\)-hyperbranching, respectively) in a mixed hypergraph, we mean a mixed subhypergraph which, after a proper orientation of its hyperedges, can become an \(r\)-hyperarborescence (\(R\)-hyperbranching, respectively). A matroid-rooted mixed hyperarborescence is a triple \((\mathcal{T}, r, s)\) where \(\mathcal{T}\) is a mixed \(r\)-hyperarborescence and \(s\) is an element of \(S\) mapped to \(r\). We define a matroid-based packing of matroid-rooted mixed hyperarborescences in \((\mathcal{F}, \mathcal{M}, S, \pi)\) as a set \(\{(\mathcal{T}_1, r_1, s_1), \ldots, (\mathcal{T}_{|S|}, r_{|S|}, s_{|S|})\}\) of pairwise (hyper-and-dyperedge)-disjoint matroid-rooted mixed hyperarborescences in \((\mathcal{F}, \mathcal{M}, S, \pi)\) such that, by a proper orientation of the hyperedges of each \((\mathcal{T}_i, r_i, s_i)\), one can get a matroid-based packing of matroid-rooted hyperarborescences \(\{(\mathcal{T}_1, r_1, s_1), \ldots, (\mathcal{T}_{|S|}, r_{|S|}, s_{|S|})\}\) with the same roots. When a rooted (matroid-rooted, respectively) mixed hypergraph has no dyperedges, it is a rooted (matroid-rooted, respectively) hypergraph. We call a mixed hyperarborescence without dyperedges a hypertree.

Figure 2: \(\overline{T}_1\) is a spanning \(r_1\)-hyperarborescence while \(\overline{T}_2\) is a reachability \(r_2\)-hyperarborescence of the dypergraph.
3. Previous results

First we mention the strong form of Theorem 1 that considers a more general problem where we want to find a packing of spanning $\mathcal{R}$-branchings in $\bar{G}$.

**Theorem 2** ([6]). In a rooted digraph $(\bar{G} = (V, A), \mathcal{R})$, there exists a packing of spanning $\mathcal{R}$-branchings if and only if

$$\varrho_A(X) \geq p^\mathcal{R}(X)$$

(4)

holds for all $\emptyset \neq X \subseteq V$.

This result was generalized for rooted dypergraphs by Frank, T. Király and Z. Király [10] by observing that a dypergraph satisfying condition (5) of the following theorem (which is an equivalent form of the result of [10] using the notion of hyperbranchings) can be trimmed to a digraph satisfying (4). We should also cite here the paper of Frank, T. Király and Kriesell [11] for the corresponding result on packing hypertrees.

**Theorem 3** ([10]). In a rooted dypergraph $(\bar{H} = (V, A), \mathcal{R})$, there exists a packing of spanning $\mathcal{R}$-hyperbranchings if and only if

$$\varrho_A(X) \geq q^\mathcal{R}_A(X)$$

(5)

holds for all $\emptyset \neq X \subseteq V$.

A generalization of Theorem 2 for reachability branchings was given by Kamiyama, Katoh and Takizawa [13], as follows.

**Theorem 4** ([13]). There exists a packing of reachability $\mathcal{R}$-branchings in a rooted digraph $(\bar{G} = (V, A), \mathcal{R})$ if and only if

$$\varrho_A(X) \geq q^P_A(X)$$

(6)

holds for all $\emptyset \neq X \subseteq V$.

Observe that, (4) holds if and only if (6) holds and each vertex $v \in V$ is reachable from each set $R_i \in \mathcal{R}$. Bérczi and Frank [2] noted that Theorem 4 extends to dypergraphs.


**Theorem 5** ([5]). Let $(\bar{G} = (V, A), \mathcal{M}, S, \pi)$ be a matroid-rooted digraph. There exists a matroid-based packing of matroid-rooted arborescences in $(\bar{G}, \mathcal{M}, S, \pi)$ if and only if $\pi$ is $\mathcal{M}$-independent and

$$\varrho_A(X) \geq r_{\mathcal{M}}(S) - r_{\mathcal{M}}(S_X)$$

(7)

holds for all $\emptyset \neq X \subseteq V$.

**Theorem 6** ([15]). Let $(\bar{G} = (V, A), \mathcal{M}, S, \pi)$ be a matroid-rooted digraph. There exists a reachability-based packing of matroid-rooted arborescences in $(\bar{G}, \mathcal{M}, S, \pi)$ if and only if $\pi$ is $\mathcal{M}$-independent and

$$\varrho_A(X) \geq r_{\mathcal{M}}(S_{P_A(X)}) - r_{\mathcal{M}}(S_X)$$

(8)

holds for all $\emptyset \neq X \subseteq V$.

In Section 4, we extend Theorems 5 and 6 to dypergraphs.

An extension of Theorem 1 for mixed graphs was given by Frank [9] as an application of an orientation result. We provide a common generalization of this result and Theorem 2 later.

**Theorem 7** ([9]). There exists a packing of $k$ spanning mixed $\mathcal{R}$-arborescences in a mixed graph $F = (V, E \cup A)$ if and only if

$$e_E(P) \geq \sum_{i=1}^{r}(k - \varrho_A(V_i))$$

(9)

holds for every partition $P = \{r \in V_0, V_1, \ldots, V_t\}$ of $V$.  

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4. Reachability-based packing of matroid-rooted hyperarborescences

The following theorem, which is the main contribution of the present paper, provides a common generalization of Theorems 3 and 6.

**Theorem 8.** Let $(\mathcal{H} = (V, A), M, S, \pi)$ be a matroid-rooted digraph. There exists a reachability-based packing of matroid-rooted hyperarborescences in $(\mathcal{H}, M, S, \pi)$ if and only if $\pi$ is $M$-independent and

$$g_A(X) \geq r_M(S_{P_A(X)}) - r_M(S_X)$$

holds for all $X \subseteq V$.

**Proof.** To prove the necessity, let $\{(\vec{T}_1, r_1, s_1), \ldots, (\vec{T}_{|S|}, r_{|S|}, s_{|S|})\}$ be a reachability-based packing of matroid-rooted hyperarborescences in $(\mathcal{H}, M, S, \pi)$. For any $v \in V$, since $S_v \subseteq B_v$ and $B_v$ is independent in $M$, so is $S_v$, and hence $\pi$ is $M$-independent. Let now $X \subseteq V$ and $B = \bigcup_{v \in X} B_v$. Since $\text{Span}_M$ is monotone, $B_v$ is a base of $S_{P_A(v)}$ and by definition of $P_A(X)$, we have $\text{Span}_M(B) = \bigcup_{v \in X} \text{Span}_M(B_v) \supseteq \bigcup_{v \in X} S_{P_A(v)} = S_{P_A(X)}$. Then, since $r_M$ is monotone, $(\ast)$ $r_M(B) \geq r_M(S_{P_A(X)})$.

For each matroid-root $s_i \in B \setminus S_X$, there exists a vertex $v \in X$ such that $s_i \in B_v$ and then since $\vec{T}_i$ is an $r_i$-hyperarborescence and $v \in Q_{M}(\vec{T}_i)(r_i) \cap X$, there exists a dyperedge of $\vec{T}_i$ that enters $X$. Since these matroid-rooted hyperarborescences are dyperedge-disjoint, $r_M$ is subcardinal, submodular, and monotone, and by $(\ast)$, we have $g_A(X) \geq |B \setminus S_X| \geq r_M(B \setminus S_X) \geq r_M(B \cup S_X) - r_M(S_X) \geq r_M(B) - r_M(S_X) \geq r_M(S_{P_A(X)}) - r_M(S_X)$ that is, (10) is satisfied.

To prove the sufficiency, let $(\mathcal{H} = (V, A), M, S, \pi)$ be a matroid-rooted digraph such that $\pi$ is $M$-independent and (10) holds. First we define a matroid-rooted digraph $(\vec{G} = (V', A), M, S, \pi)$ for which the conditions of Theorem 6 hold. We define $V' := V \cup A$ hence $\pi$ is still well defined and $M$-independent in $V'$. Let $A_1 := \{(Z, z) : (Z, z) \in A\}$ and $A_2 := \{t(Z, z) : (Z, z) \in A, t \in Z \setminus z\}$. Let $A := A_1 \cup (r_M(S) \cdot A_2)$ where $r_M(S) \cdot A_2$ denotes the multiset consisting of the union of $r_M(S)$ copies of $A_2$. For the construction see Figure 3.

![Figure 3: The construction.](image)

Observe that $g_A(X) \geq r_M(S_{P_A(X)}) - r_M(S_X)$ for a subset $X \subseteq V'$ whenever there exist a dyperedge $(Z, z)$ and a tail vertex $t \in Z \setminus z$ in $\vec{H}$ such that, in $\vec{G}$, $(Z, z) \in X$ and $t \notin X$ since then the $r_M(S)$ copies of the arc $t(Z, z)$ enter $X$ in $\vec{G}$ and hence $g_A(X) \geq r_M(S) \geq r_M(S_{P_A(X)}) - r_M(S_X)$. Moreover, if there is no such dyperedge, then $g_A(X) = g_A(X \cap V), r_M(S_{P_A(X)}) = r_M(S_{P_A(X \cap V)}), r_M(S_X) = r_M(S_{X \cap V})$ and hence (8) follows from (10).

Therefore, there exists a reachability-based packing of matroid-rooted arborescences $\{(\vec{T}_1, r_1, s_1), \ldots, (\vec{T}_{|S|}, r_{|S|}, s_{|S|})\}$ in $(\vec{G}, M, S, \pi)$ by Theorem 6. We define $\vec{T}_i$ $(i = 1, \ldots, |S|)$ to be the subdigraph of $\vec{H}$ induced by dyperedges $(Z, z) \in A$ such that the vertex $(Z, z)$ has out-degree 1 in $\vec{T}_i$. It is easy to check that $\vec{T}_i$ is an $r_i$-hyperarborescence with matroid-root $s_i$ and the set of vertices of $\vec{T}_i$ with in-degree 1 is the same as the set of vertices in $V$ of in-degree 1 in $\vec{T}_i$. Moreover, the hyperarborescences $\vec{T}_1, \ldots, \vec{T}_{|S|}$ are dyperedge-disjoint since each vertex $(Z, z) \in A$ has out-degree 1 in $\vec{G}$. Hence, as the reachability of the vertices in $V$ from $r_i$ coincides in $\vec{T}_i$ and $\vec{T}_i$ $(i = 1, \ldots, |S|)$, $\{(\vec{T}_1, r_1, s_1), \ldots, (\vec{T}_{|S|}, r_{|S|}, s_{|S|})\}$ is a reachability-based packing of matroid-rooted hyperarborescences in $(\mathcal{H}, M, S, \pi)$. ■
As a corollary of Theorem 8 (or from Theorem 5 with a proof similar to the previous one), one can get the following result on matroid-based packing of matroid-rooted hyperarborescences.

**Corollary 1.** Let \( \vec{H} = (V, A, M, S, \pi) \) be a matroid-rooted dypergraph. There exists a matroid-based packing of matroid-rooted hyperarborescences in \( (\vec{H}, M, S, \pi) \) if and only if \( \pi \) is \( M \)-independent and

\[
\varrho_A(X) \geq r_M(S) - r_M(S_X)
\]

(11)

holds for all \( \emptyset \neq X \subseteq V \).

Similarly, one can get Theorem 3 and the result of Bérczi and Frank [2], that is, the extensions of Theorems 2 and 4 for dypergraphs.

5. Algorithmic aspects

Bérczi and Frank [1] gave a TDI polyhedral description of the – so called – arborescence packable subgraphs. Using this result it can be shown that there is a polynomial algorithm to find a minimum cost packing of spanning (reachability, resp.) \( \mathcal{R} \)-branchings for any cost function on the arc-set of a rooted digraph \( \vec{G}, \mathcal{R} \). [5] provided also an algorithm for the problem of minimum cost matroid-based packing of matroid-rooted arborescences and recently Bérczi, T. Király and Kobayashi [3, 4] solved the problem of minimum cost reachability-based packing of matroid-rooted arborescences.

As noted before, Frank, T. Király and Z. Király [10] showed that it is possible to trim a dypergraph satisfying (5) to a digraph satisfying (4). However, this method fails to work for the generalization of the problem where we are seeking minimum cost dyperedge-disjoint spanning hyperbranchings as Figure 4 shows. Note that the minimum cost spanning hyperarborescence of solid, red dyperedges of the dypergraph on the left-hand side of the figure has cost 0 while in the trimmed digraph on the right-hand side there is only one spanning arborescence and it has cost 1.

![Figure 4: The trimming operation does not preserve minimum cost arborescence packings.](image)

Let us now assume that, in a matroid-rooted dypergraph \( (\vec{H}, M, S, \pi) \), a cost function \( c \) is given on the dyperedges. Recall the proof of Theorem 8. Observe that if we take a cost function \( c' \) on the arc-set of the defined digraph to be 0 on the arcs with a head in \( A \) and \( c((Z, z)) \) on the arc with a tail \( (Z, z) \) for every \( (Z, z) \in A \), then a minimum cost reachability-based packing of matroid-rooted arborescences in \( (\vec{G}, M, S, \pi) \) gives rise to a minimum cost reachability-based packing of matroid-rooted hyperarborescences in \( (\vec{H}, M, S, \pi) \) with the same cost. By using the above algorithms and similar deductions, we obtain the following result.

**Theorem 9.** There exists polynomial algorithms that, for an input consisting of a dypergraph \( \vec{H} = (V, A) \), a cost function \( c \) on \( A \), and a family \( \mathcal{R} \) of some non-empty subsets of \( V \) or a matroid \( M \) on \( S \) along with a map \( \pi : S \rightarrow V \), output the following:

(a) a minimum cost packing of spanning \( \mathcal{R} \)-hyperbranchings in \( (\vec{H}, \mathcal{R}) \),
(b) a minimum cost packing of reachability \( \mathcal{R} \)-hyperbranchings in \( (\vec{H}, \mathcal{R}) \),
(c) a minimum cost matroid-based packing of matroid-rooted hyperarborescences in \( (\vec{H}, M, S, \pi) \),
(d) a minimum cost reachability-based packing of matroid-rooted hyperarborescences in \( (\vec{H}, M, S, \pi) \).
6. Packing mixed hyperarborescences

A common generalization of Theorem 7 and Corollary 1 can be formulated as follows.

**Theorem 10.** There exists a matroid-based packing of matroid-rooted mixed hyperarborescences in a matroid-rooted mixed hypergraph \((F = (V, E \cup A), \mathcal{M}, S, \pi)\) if and only if \(\pi\) is \(\mathcal{M}\)-independent and

\[ e_E(P) \geq \sum_{i=1}^{\ell} (r_M(S) - r_M(SV_i) - \varrho_A(V_i)) \]  

holds for every partition \(P = \{V_0, V_1, \ldots, V_\ell\}\) of \(V\).

We prove this theorem using the method of Frank [9]. To this end, we need the following general orientation result on hypergraphs. The proof of [8, Theorem 15.4.13] (the corresponding result for graphs) – with the necessary straightforward modifications – can be extended to hypergraphs. We mention that this result can also be obtained by using the techniques from [10].

**Theorem 11.** Let \(H = (V, E)\) be a hypergraph and \(h\) an integer-valued, intersecting supermodular function (with possible negative values) such that \(h(V) = 0\). There exists an orientation of \(H\) that covers \(h\) if and only if

\[ e_E(P) \geq \sum_{i=1}^{\ell} h(V_i) \]  

holds for every partition \(P = \{V_0, V_1, \ldots, V_\ell\}\) of \(V\).

Note that in (12) and in (13) the index \(i\) starts at 1 (and not at 0). This means that we consider here all the subpartitions of \(V\).

Now we are ready to prove Theorem 10.

**Proof of Theorem 10.** Let \((F = (V, E \cup A), \mathcal{M}, S, \pi)\) be a matroid-rooted mixed hypergraph. Let us introduce the following function \(h^*\), which is integer-valued, intersecting supermodular and satisfies \(h^*(V) = 0\).

\[ h^*(X) = \begin{cases} 
   r_M(S) - r_M(SX) - \varrho_A(X) & \text{if } \emptyset \neq X \subseteq V, \\
   0 & \text{if } X = \emptyset.
\end{cases} \]

Theorem 11, applied for \((V, E)\) (the undirected part of the mixed hypergraph \(F\)) and \(h^*\), provides the following result.

**Lemma 1.** There exists an orientation of a matroid-rooted mixed hypergraph \((F, \mathcal{M}, S, \pi)\) satisfying (11) if and only if (12) is satisfied.

We get Theorem 10 by Corollary 1 and Lemma 1.

Note that Theorem 10 reduces to the following result when \(A = \emptyset\). This result is a generalization of a result of Katoh and Tanigawa [14] for hypergraphs. Recall that by a matroid-based packing of matroid-rooted hypertrees we mean that the hypertrees can be oriented such that we get a matroid-based packing of matroid-rooted hyperarborescences with the same roots.

**Corollary 2.** Let \((H, \mathcal{M}, S, \pi)\) be a matroid-rooted hypergraph. There exists a matroid-based packing of matroid-rooted hypertrees in \((H, \mathcal{M}, S, \pi)\) if and only if \(\pi\) is \(\mathcal{M}\)-independent and

\[ e_E(P) \geq \sum_{X \in P} (r_M(S) - r_M(SX)) \]  

holds for every partition \(P\) of \(V\).
Remark 3. We note that Theorem 10 in the case where $F$ is a mixed graph is a common generalization of the above mentioned result of Katoh and Tanigawa [14] and Theorem 5.

By Remark 2, we get the following corollary of Theorem 10 that, in the case where $F$ is a mixed graph, generalizes Theorem 7 for packing of mixed branchings.

Corollary 3. In a rooted mixed hypergraph $(F = (V, E \cup A), R)$, there exists a packing of spanning mixed $R$-hyperbranchings if and only if

$$e_E(\mathcal{P}) \geq \sum_{i=1}^{\ell} (q_{E \cup A}(V_i) - \varrho_A(V_i))$$

holds for every partition $\mathcal{P} = \{V_0, V_1, \ldots, V_\ell\}$ of $V$.

7. Concluding remarks

We finish this paper with some remarks on other possible generalizations.

7.1. Packing of reachability mixed-arborescences

The first problem is about packing reachability mixed-arborescences. We just mention the orientation version of the problem. Let $(F = (V, E \cup A), R)$ be a rooted mixed graph. For a set $X \subseteq V$, we denote by $Q_{E \cup A}(X)$ the set of vertices that can be reached from $X$ in $F$ and by $q_R^{E \cup A}(X)$ the number of indices $i$ such that $R_i \cap X = \emptyset$ and $Q_{E \cup A}(R_i) \cap X \neq \emptyset$. When does there exist an orientation $\vec{E}$ of $E$ such that $(V, \vec{E} \cup A)$ covers $q_R^{E \cup A}$? Let us consider the following two conditions that are clearly necessary: for every partition $\mathcal{P} = \{V_0, V_1, \ldots, V_\ell\}$ of $V$,

$$e_E(\mathcal{P}) \geq \sum_{i=1}^{\ell} (q_{E \cup A}(V_i) - \varrho_A(V_i))$$

(16)

$$e_E(\mathcal{P}) \geq \sum_{i=1}^{\ell} (q_{E \cup A}(V \setminus V_i) - \varrho_A(V \setminus V_i)).$$

(17)

The following example shows that conditions (16) and (17) are not sufficient. Let $F = (V, E \cup A)$ and $R = \{\{r_1\}, \{r_2\}\}$ be defined as follows. $V = \{a, b, c, d\}$, $E = \{ab\}$, $A = \{ca, cb, ad, bd\}$, $r_1 = a$ and $r_2 = b$. It is easy to check that (16) and (17) are satisfied. However, the required orientation does not exist since the edge $ab$ should be oriented in both directions.

7.2. Infinite dypergraphs

In this paper, we considered finite dypergraphs; however, some results can also be proved for infinite dypergraphs. In a recent paper, Joó [12] showed that Theorem 2 is also true in infinite digraphs that contain no forward-infinite paths. Hence using the proof technique of Theorem 8 to this result one can extend Theorem 3 to infinite dypergraphs that contain no forward-infinite paths.

7.3. Covering intersecting bi-set families under matroid constraints in dypergraphs

Finally, we mention that Bérczi, T. Király, Kobayashi [3] have provided an abstract result on covering intersecting bi-set families under matroid constraints that generalizes Theorem 6 and another result of Bérczi and Frank [2]. Without going into details, we just mention that their proof also works for dypergraphs.

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