

# New Filtering algorithm for AtMostNValue and its weighted variant: a Lagrangian approach

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# Outline

1. AtMostNValue and AtMostWValue
2. Linear relaxation and reduced cost-based filtering
3. Lagrangian approach
  - Basics of LR: why does it give a lower bound
  - Comparing LP and LR cost based filtering
4. Solving the Lagrangian dual
5. Some results

# NValue

$$\text{NVALUE}([X_1, \dots, X_n], N) \iff |\{j \mid \exists X_i \in \mathcal{X}, X_i = j\}| = N$$

Enforce N to be **the number of distinct values** appearing in the set X of variables

$$\begin{aligned} & \text{ATMOSTNVALUE}([X_1, \dots, X_n], N) \\ & \left( |\{j \mid \exists X_i \in \mathcal{X}, X_i = j\}| \leq N \right) \\ & \quad + \\ & \text{ATLEASTNVALUE}([X_1, \dots, X_n], N) \\ & \left( |\{j \mid \exists X_i \in \mathcal{X}, X_i = j\}| \geq N \right) \end{aligned}$$

# AtMostNValue

$\text{ATMOSTNVALUE}([X_1, \dots, X_6], N)$

$$D(X_1) = \{1, 2, 3, 4, 5, 6\}$$

$$D(X_2) = \{2, 4\}$$

$$D(X_3) = \{1, 2\}$$

$$D(X_4) = \{1, 2, 3\}$$

$$D(X_5) = \{4, 5\}$$

$$D(X_6) = \{4, 5\}$$

$$D(N) = \{1, 2\}$$

**A solution:**

$\text{ATMOSTNVALUE}([2, 2, 2, 2, 4, 4, 2], 2)$

# AtMostNValue

ATMOSTNVALUE( $[X_1, \dots, X_6], N$ )

$$D(X_1) = \{1, 2, 3, 4, 5, 6\}$$

$$D(X_2) = \{2, 4\}$$

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$$D(X_4) = \{1, 2, 3\}$$

$$D(X_5) = \{4, 5\}$$

$$D(X_6) = \{4, 5\}$$

$$D(N) = \{1, 2\}$$

$$D(X_1) = \{1, 2, \del{3}, 4, 5, \del{6}\}$$

$$D(X_2) = \{2, 4\}$$

$$D(X_3) = \{1, 2\}$$

$$D(X_4) = \{1, 2, \del{3}\}$$

$$D(X_5) = \{4, 5\}$$

$$D(X_6) = \{4, 5\}$$

$$D(N) = \{\del{1}, 2\}$$

A solution:

ATMOSTNVALUE( $[2, 2, 2, 2, 4, 4, 2], 2$ )

# AtMostNValue

ATMOSTNVALUE( $[X_1, \dots, X_6], N$ )

$$D(X_1) = \{1, 2, 3, 4, 5, 6\}$$

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$$D(X_6) = \{4, 5\}$$

$$D(N) = \{1, 2\}$$

$$D(X_1) = \{1, 2, \cancel{3}, 4, 5, \cancel{6}\}$$

$$D(X_2) = \{2, 4\}$$

$$D(X_3) = \{1, 2\}$$

$$D(X_4) = \{1, 2, \cancel{3}\}$$

$$D(X_5) = \{4, 5\}$$

$$D(X_6) = \{4, 5\}$$

$$D(N) = \{\cancel{1}, 2\}$$

$$D(X_3) \cap D(X_5) = \emptyset$$

A solution:

ATMOSTNVALUE( $[2, 2, 2, 2, 4, 4, 2], 2$ )

# AtMostNValue

ATMOSTNVALUE( $[X_1, \dots, X_6], N$ )

$$D(X_1) = \{1, 2, 3, 4, 5, 6\}$$

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$$D(X_6) = \{4, 5\}$$

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$$D(X_3) = \{1, 2\}$$

$$D(X_4) = \{1, 2, \del{3}\}$$

$$D(X_5) = \{4, 5\}$$

$$D(X_6) = \{4, 5\}$$

$$D(N) = \{\del{1}, 2\}$$

- Enforcing GAC is NP-Hard
- [Hebrard et al, 2006], [Beldiceanu et al, 2001]:
  - Lower bound of N obtained by a greedy computing an independent set
  - Best lower bound obtained with a linear relaxation

# AtMostNValue - AtMostWValue

- AtMostNValue can be generalized by considering a weight (or cost) for each value:

$$\text{ATMOSTWVALUE}([X_1, \dots, X_n], W, w)$$



$$\sum_{\{j \mid \exists X_i \in \mathcal{X}, X_i=j\}} w(j) \leq W$$

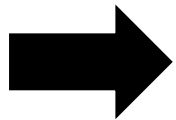
- Modeling : a value = a resource
  - The total number of resources available is bounded
  - The total available cost of resources is bounded



# AtMostNValue – Value representation

$\text{ATMOSTNVALUE}([X_1, \dots, X_n], [Y_1, \dots, Y_m], N)$

$Y_j \in \{0, 1\}$  : value  $j$  occurs at least once

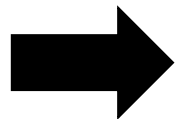


express reasoning on mandatory values

Example:

$$D(X_1) = \{1, 2\}, D(X_2) = \{2, 3\}, D(N) = \{2\}$$

$$D(X_3) = \{2, 4\}$$



propagate  $Y_2 = 1$

# Linear relaxation

ATMOSTWVALUE( $[X_1, \dots, X_n], [Y_1, \dots, Y_m], W, w$ )

**Minimize:**  $w = \sum_{1 \leq j \leq m} w_j y_j$

**Subject to:**  $\sum_{j \in D(X_i)} y_j \geq 1 \quad \forall i \in [1, n]$

$y_j \geq 0 \quad \forall j \in [1, m]$

- Assuming all weights (costs) are positive

# Reduced-cost filtering with the linear relaxation

Minimize:  $w = \sum_{1 \leq j \leq m} w_j y_j$

Subject to:  $\sum_{j \in D(X_i)} y_j \geq 1 \quad \forall i \in [1, n] \quad (\alpha_i \geq 0)$

$y_j \geq 0 \quad \forall j \in [1, m]$

- Linear reduced cost for each  $y_j$  such that  $y_j^* = 0$

$$r_j^* = w_j - \sum_{i|j \in D(X_i)} \alpha_i^*$$

- In the LP case, reduced-cost based filtering is restricted to forbidden values:

$$\forall j \in [1, m] \text{ s.t. } y_j^* = 0 \quad w^* + r_j^* > \overline{W} \implies Y_j \neq 1$$

# Lagrangian relaxation

Primal

$$\begin{aligned} \text{Min } z &= \sum_j w_j y_j \\ \sum_{j \in D(X_i)} y_j &\geq 1 \quad \forall i \\ y_j &\in \{0, 1\} \quad \forall j \end{aligned} \quad \boxed{P}$$

# Lagrangian relaxation

Primal


$$\begin{array}{l} \text{Min } z = \sum_j w_j y_j \\ \sum_{j \in D(X_i)} y_j \geq 1 \quad \forall i \quad (\lambda_i) \\ y_j \in \{0, 1\} \quad \forall j \end{array} \quad \boxed{P}$$

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For any  $\lambda \geq 0$  : Lagrangian subproblem

$$\begin{aligned} \text{Min } w(\lambda) &= \sum_j w_j y_j + \sum_i \lambda_i \left(1 - \sum_{j \in D(X_i)} y_j\right) \\ y_j &\in \{0, 1\} \quad \forall j \end{aligned} \quad \boxed{L(\lambda)}$$


# Lagrangian relaxation

Primal

$$\begin{array}{l}
 \text{Min } z = \sum_j w_j y_j \\
 \sum_{j \in D(X_i)} y_j \geq 1 \quad \forall i \quad (\lambda_i) \\
 y_j \in \{0, 1\} \quad \forall j
 \end{array}
 \quad \boxed{P}$$

For any  $\lambda \geq 0$  : Lagrangian subproblem

$$\begin{array}{l}
 \text{Min } w(\lambda) = \sum_j w_j y_j + \sum_i \lambda_i \underbrace{\left(1 - \sum_{j \in D(X_i)} y_j\right)}_{\substack{\geq 0 \\ \leq 0}} \\
 y_j \in \{0, 1\} \quad \forall j
 \end{array}
 \quad \boxed{L(\lambda)}$$

Consider a feasible solution  $\bar{y}$  of  $P$  with value  $\bar{z}$

So we have  $\bar{w}(\lambda) \leq \bar{z}$

# Lagrangian relaxation

Primal

$$\begin{aligned} \text{Min } z &= \sum_j w_j y_j \\ \sum_{j \in D(X_i)} y_j &\geq 1 \quad \forall i \\ y_j &\in \{0, 1\} \quad \forall j \end{aligned} \quad \boxed{P}$$

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For any  $\lambda \geq 0$  :

Any feasible solution  $\bar{y}$  of  $P$  is also feasible for  $L(\lambda)$  and  $\bar{w}(\lambda) \leq \bar{z}$

So we have :  $w^*(\lambda) \leq z^*$



# Lagrangian relaxation

Primal

$$\begin{aligned} \text{Min } z &= \sum_j w_j y_j \\ \sum_{j \in D(X_i)} y_j &\geq 1 \quad \forall i \\ y_j &\in \{0, 1\} \quad \forall j \end{aligned} \quad \boxed{P}$$

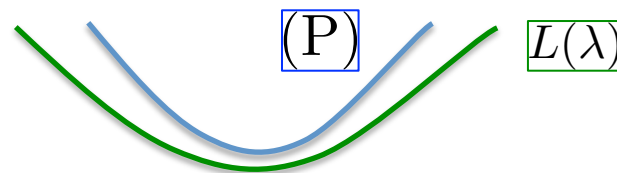
For any  $\lambda \geq 0$  : Lagrangian subproblem

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For any  $\lambda \geq 0$  :

Any feasible solution  $\bar{y}$  of  $P$  is also feasible for  $L(\lambda)$  and  $\bar{w}(\lambda) \leq \bar{z}$

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# Lagrangian relaxation

Primal

$$\begin{aligned} \text{Min } z &= \sum_j w_j y_j \\ \sum_{j \in D(X_i)} y_j &\geq 1 \quad \forall i \\ y_j &\in \{0, 1\} \quad \forall j \end{aligned} \quad \boxed{P}$$

For any  $\lambda \geq 0$  : Lagrangian subproblem

$$\begin{aligned} \text{Min } w(\lambda) &= \sum_j w_j y_j + \sum_i \lambda_i \left(1 - \sum_{j \in D(X_i)} y_j\right) \\ &= \sum_j \underbrace{\left(w_j - \sum_{\{i | j \in D(X_i)\}} \lambda_i\right)}_{q_j} y_j + \sum_i \lambda_i \end{aligned} \quad \boxed{L(\lambda)}$$

- Solving the Lagrangian subproblem optimally for any positive lambda provides a lower bound for  $W$
- Complexity is in  $O(nm)$  to check the sign of  $q_j$ 
  - If  $q_j$  is negative, set  $y_j$  to 1
  - If  $q_j$  is positive, set  $y_j$  to 0

$$q_j = w_j - \sum_{\{i | j \in D(X_i)\}} \lambda_i$$

# Lagrangian relaxation - filtering

- $q_j$  can be seen as a “Lagrangian reduced cost”:

*(the increase/decrease of the objective value for setting  $y_j$  to 1)*

- The filtering rules are simply :

$$y_j^* = 0 \text{ and } w^*(\lambda) + q_j > \bar{W} \implies Y_j \neq 1 \quad (\text{forbidden values})$$

$$y_j^* = 1 \text{ and } w^*(\lambda) - q_j > \bar{W} \implies Y_j \neq 0 \quad (\text{mandatory values})$$

- Filtering can be done from any values of  $\lambda$

# Lagrangian relaxation - filtering

- The filtering rules are simply :

$$w^*(\lambda) + (1 - y_j^*)q_j > \overline{W} \implies Y_j \neq 1 \quad \text{(forbidden values)}$$

$$w^*(\lambda) - y_j^*q_j > \overline{W} \implies Y_j \neq 0 \quad \text{(mandatory values)}$$

- If  $\lambda_j = \alpha_j^*$  then  $q_j = r_j^*$  (Lagrangian and linear reduced costs are the same)

$$r_j^* = w_j - \sum_{\{i|j \in D(X_i)\}} \alpha_i^*$$

$$q_j = w_j - \sum_{\{i|j \in D(X_i)\}} \lambda_i$$

- Replacing  $q_j$  with  $r_j^*$  and since  $r_j^*y_j^* = 0$  (complementary slackness), we have the LP filtering:  $w^* + r_j^* > \overline{W} \implies Y_j \neq 1$
- With the same optimal multipliers, LP and LR perform the same filtering (forbidden values)

# Example

$$D(X_1) = \{1, 2\} \quad D(X_3) = \{4, 5\}$$
$$D(X_2) = \{2, 3\} \quad N = \{1, 2\}$$

$$w = y_1 + y_2 + y_3 + y_4 + y_5$$

$$y_1 + y_2 \geq 1$$

$$y_2 + y_3 \geq 1$$

$$y_4 + y_5 \geq 1$$

$$y_j \geq 0 \quad \forall j \in [1, 5]$$

LP

$$w(\lambda_1, \lambda_2, \lambda_3) = y_1(1 - \lambda_1) + y_2(1 - \lambda_1 - \lambda_2)$$
$$+ y_3(1 - \lambda_2) + y_4(1 - \lambda_3) + y_5(1 - \lambda_3)$$
$$+ (\lambda_1 + \lambda_2 + \lambda_3)$$
$$y_j \in \{0, 1\} \quad \forall j \in [1, 5]$$

LR subpb

# Example

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$$+ (\lambda_1 + \lambda_2 + \lambda_3)$$
$$y_j \in \{0, 1\} \quad \forall j \in [1, 5]$$

LR subpb

$\lambda_1$	$\lambda_2$	$\lambda_3$
0.8	0.8	0.8

# Example

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$$+ (\lambda_1 + \lambda_2 + \lambda_3)$$
$$y_j \in \{0, 1\} \quad \forall j \in [1, 5]$$

LR subpb

$\lambda_1$	$\lambda_2$	$\lambda_3$	$q_1$	$q_2$	$q_3$	$q_4$	$q_5$
0.8	0.8	0.8	0.2	-0.6	0.2	0.2	0.2

# Example

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$$y_j \in \{0, 1\} \quad \forall j \in [1, 5]$$

LR subpb

$\lambda_1$	$\lambda_2$	$\lambda_3$
0.8	0.8	0.8

$q_1$	$q_2$	$q_3$	$q_4$	$q_5$
0.2	-0.6	0.2	0.2	0.2

$y_1^*$	$y_2^*$	$y_3^*$	$y_4^*$	$y_5^*$
0	1	0	0	0



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LR subpb

$\lambda_1$	$\lambda_2$	$\lambda_3$
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$y_1^*$	$y_2^*$	$y_3^*$	$y_4^*$	$y_5^*$
0	1	0	0	0

$$w^*(\lambda) = 1.8$$

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$$+ y_3(1 - \lambda_2) + y_4(1 - \lambda_3) + y_5(1 - \lambda_3)$$

$$+ (\lambda_1 + \lambda_2 + \lambda_3)$$

$$y_j \in \{0, 1\} \quad \forall j \in [1, 5]$$

LR subpb

$\lambda_1$	$\lambda_2$	$\lambda_3$
0.8	0.8	0.8

$q_1$	$q_2$	$q_3$	$q_4$	$q_5$
0.2	-0.6	0.2	0.2	0.2

$y_1^*$	$y_2^*$	$y_3^*$	$y_4^*$	$y_5^*$
0	1	0	0	0

$$w^*(\lambda) = 1.8$$

$$w^*(\lambda) - q_2 = 2.4 > \bar{N} \implies Y_2 \neq 0$$

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$$y_j \geq 0 \quad \forall j \in [1, 5]$$

LP

$$w(\lambda_1, \lambda_2, \lambda_3) = y_1(1 - \lambda_1) + y_2(1 - \lambda_1 - \lambda_2) + y_3(1 - \lambda_2) + y_4(1 - \lambda_3) + y_5(1 - \lambda_3) + (\lambda_1 + \lambda_2 + \lambda_3)$$

$$y_j \in \{0, 1\} \quad \forall j \in [1, 5]$$

LR subpb

$\lambda_1$	$\lambda_2$	$\lambda_3$
0.8	0.8	0.8

$q_1$	$q_2$	$q_3$	$q_4$	$q_5$
0.2	-0.6	0.2	0.2	0.2

$y_1^*$	$y_2^*$	$y_3^*$	$y_4^*$	$y_5^*$
0	1	0	0	0

$$w^*(\lambda) = 1.8$$

$$w^*(\lambda) - q_2 = 2.4 > \bar{N} \implies Y_2 \neq 0$$

$\lambda_1$	$\lambda_2$	$\lambda_3$
0.8	0.8	0.9

$q_1$	$q_2$	$q_3$	$q_4$	$q_5$
0.2	-0.6	0.2	0.1	0.1

$y_1^*$	$y_2^*$	$y_3^*$	$y_4^*$	$y_5^*$
0	1	0	0	0

$$w^*(\lambda) = 1.9$$

$$w^*(\lambda) + q_1 = 2.1 > \bar{N} \implies Y_1 \neq 1$$

$$w^*(\lambda) + q_3 = 2.1 > \bar{N} \implies Y_3 \neq 1$$

# Example

$$D(X_1) = \{1, 2\} \quad D(X_3) = \{4, 5\}$$

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$$w = y_1 + y_2 + y_3 + y_4 + y_5$$

$$y_1 + y_2 \geq 1$$

$$y_2 + y_3 \geq 1$$

$$y_4 + y_5 \geq 1$$

$$y_j \geq 0 \quad \forall j \in [1, 5]$$

LP

$$w(\lambda_1, \lambda_2, \lambda_3) = y_1(1 - \lambda_1) + y_2(1 - \lambda_1 - \lambda_2) + y_3(1 - \lambda_2) + y_4(1 - \lambda_3) + y_5(1 - \lambda_3) + (\lambda_1 + \lambda_2 + \lambda_3)$$

$$y_j \in \{0, 1\} \quad \forall j \in [1, 5]$$

LR subpb

$\lambda_1$	$\lambda_2$	$\lambda_3$
0.8	0.8	0.8

$q_1$	$q_2$	$q_3$	$q_4$	$q_5$
0.2	-0.6	0.2	0.2	0.2

$y_1^*$	$y_2^*$	$y_3^*$	$y_4^*$	$y_5^*$
0	1	0	0	0

 $w^*(\lambda) = 1.8$ 

$$w^*(\lambda) - q_2 = 2.4 > \bar{N} \implies Y_2 \neq 0$$

$\lambda_1$	$\lambda_2$	$\lambda_3$
0.8	0.8	0.9

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0.2	-0.6	0.2	0.1	0.1

$y_1^*$	$y_2^*$	$y_3^*$	$y_4^*$	$y_5^*$
0	1	0	0	0

 $w^*(\lambda) = 1.9$ 

$$w^*(\lambda) + q_1 = 2.1 > \bar{N} \implies Y_1 \neq 1$$

$$w^*(\lambda) + q_3 = 2.1 > \bar{N} \implies Y_3 \neq 1$$

Optimal LP multipliers

$\lambda_1$	$\lambda_2$	$\lambda_3$
0	1	1

$q_1$	$q_2$	$q_3$	$q_4$	$q_5$
1	0	0	0	0

$y_1^*$	$y_2^*$	$y_3^*$	$y_4^*$	$y_5^*$
0	0	0	0	0

 $w^*(\lambda) = 2$ 

$$w^*(\lambda) + q_1 = 2.1 > \bar{N} \implies Y_1 \neq 1$$

# Lagrangian relaxation

Primal

$$\begin{aligned} \text{Min } z &= \sum_j w_j y_j \\ \sum_{j \in D(X_i)} y_j &\geq 1 \quad \forall i \\ y_j &\in \{0, 1\} \quad \forall j \end{aligned}$$

$P$

For any  $\lambda \geq 0$  : Lagrangian subproblem

$$\begin{aligned} \text{Min } w(\lambda) &= \sum_j w_j y_j + \sum_i \lambda_i \left(1 - \sum_{j \in D(X_i)} y_j\right) \\ y_j &\in \{0, 1\} \quad \forall j \end{aligned}$$

$L(\lambda)$

*Lagrangian Dual:*

$$L^* = \max_{\lambda \geq 0} w^*(\lambda)$$

# Lagrangian relaxation

Primal

$$\begin{aligned} \text{Min } z &= \sum_j w_j y_j \\ \sum_{j \in D(X_i)} y_j &\geq 1 \quad \forall i \\ y_j &\in \{0, 1\} \quad \forall j \end{aligned} \quad \boxed{P}$$

For any  $\lambda \geq 0$  : Lagrangian subproblem

$$\begin{aligned} \text{Min } w(\lambda) &= \sum_j w_j y_j + \sum_i \lambda_i \left(1 - \sum_{j \in D(X_i)} y_j\right) \\ y_j &\in \{0, 1\} \quad \forall j \end{aligned} \quad \boxed{L(\lambda)}$$

*Lagrangian Dual:*

$$L^* = \max_{\lambda \geq 0} w^*(\lambda)$$

It is known that  $L^*$  is equal to the optimal value of the LP

# Filtering algorithm based on Lagrangian relaxation

- The objective function of the Lagrangian dual is known to be concave piecewise linear
- A popular approach to solve it is to use a sub-gradient algorithm for updating the multipliers

---

## Algorithm 1: Outline of the ATMOSTWVALUE LR-based propagator

---

```
for ( $i \in [1, n]$ ) do
   $\lambda_i \leftarrow 0$  // Lagrangian multipliers initialization
 $k \leftarrow 0$ 
while (not subgradient.isStopCriterionMet()) do
  SolveSubProblem()
  FilterFromSubProblem()
  subgradient.UpdateMultipliers(k)
   $k \leftarrow k + 1$ 
```

Solving the Lagrangian dual  
And filtering along the way

# Sub-gradient algorithms

---

## Algorithm 4: subgradient algorithm

---

Step-size rule: how far the direction is followed

```
Function UpdateMultipliers (int k)
for (i ∈ [1, n]) do
    λi ← max(0, λi + μk(1 - ∑j ∈ D(Xi) yj))
```

Gives a direction (decrease or increase) the multiplier

- Violation/over-satisfaction of the relaxed constraints give a direction for improving the multipliers.
- The direction is followed using a step-size  $\mu^k$  that decreases over time.

Harmonic

$$\mu^k = \frac{1}{k}$$

Geometric

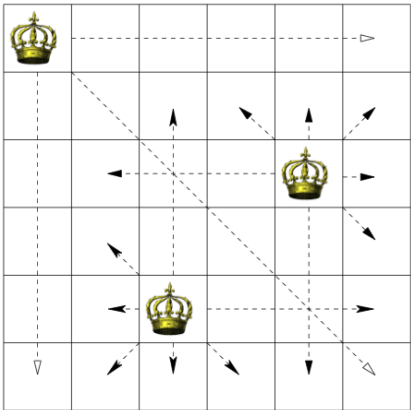
$$\mu^k = \mu^0 \times (0.95)^k$$

Newton

...



# Dominating queens



Slow subgradient  
(better convergence)

Fast  
subgradient

LP +  
Reduced-costs



Instance			CP+NVAL(Harmonic)			CP+NVAL(Newton)			CP		CP + NVAL(LP)	
n	v	Feas	Cpu	Fails	Iters	Cpu	Fails	Iters	Cpu	Fails	Cpu	Fails
6	3	Yes	0.2	7	25k	<b>0.1</b>	9	<b>3k</b>	0.2	15	0.5	9
7	4	Yes	0.5	52	128k	0.1	31	<b>9k</b>	0.1	353	4.4	93
8	5	Yes	1.0	86	210k	<b>0.2</b>	79	<b>17k</b>	0.7	2275	18.8	259
8	4	No	23.3	<b>1796</b>	2767k	<b>5.1</b>	6260	<b>299k</b>	155.6	1074789	222.8	2596
9	5	Yes	14.7	<b>862</b>	1426 k	<b>3.4</b>	1593	<b>157k</b>	186.8	920666	153.7	884

- The filtering of LR outperforms the state-of-the art propagator
- LR can be fast (faster than LP) although the bounds are the same
- LR can filter more than LP

# Conclusion

- Simple and powerful propagator for useful NP-Hard global constraints
- A propagator not meant to be used by default but really make sense when (weighted) independent set is at the heart of the problem:
  - Example: facility location
- CP models up to being competitive with MIP on facility location benchmark

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