



# Detecting induced subgraphs

Benjamin Lévêque<sup>1</sup>

*Laboratoire G-SCOP  
Grenoble, France*

David Y. Lin<sup>2</sup>

*Princeton University  
Princeton, New Jersey*

Frédéric Maffray<sup>3</sup>

*Laboratoire G-SCOP  
Grenoble, France*

Nicolas Trotignon<sup>4</sup>

*Centre d'Economie de la Sorbonne  
Paris, France*

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## Abstract

An *s-graph* is a graph with two kind of edges: *subdivisible* edges and *real* edges. A *realisation* of an s-graph  $B$  is any graph obtained by subdividing subdivisible edges of  $B$  into paths of length at least one. Given an s-graph  $B$ , we study the decision problem  $\Pi_B$ . Its instance is any graph  $G$ , its question is “Does  $G$  contains a realisation of  $B$  as an induced subgraph?”. For several  $B$ 's, the complexity is known and here we give the complexity for several more. We also provide results on the problem of detecting an induced cycle through two prescribed vertices.

*Keywords:* detecting, induced, subgraphs.

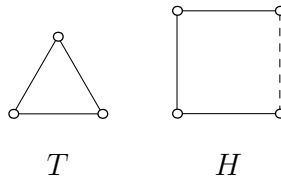


Fig. 1. S-graphs yielding trivially polynomial problems

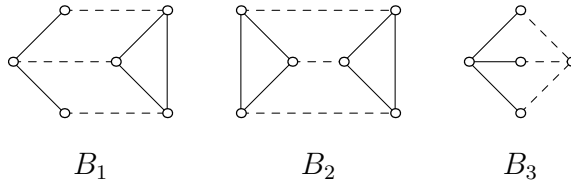


Fig. 2. Pyramids, prisms and thetas

## 1 Introduction

In this paper graphs are simple and finite. A *subdivisible graph* (*s-graph* for short) is a triple  $B = (V, D, F)$  such that  $B' = (V, D \cup F)$  is a graph and  $D \cap F = \emptyset$ . The edges in  $D$  are said to be *real edges* of  $B$  while the edges in  $F$  are said to be *subdivisible edges* of  $B$ . A *realisation* of  $B$  is a graph obtained from  $B$  by subdividing edges of  $F$  into paths of length at least one. The problem  $\Pi_B$  is the decision problem whose input is a graph  $G$  and whose question is "Does  $G$  contain a realisation of  $B$  as an induced subgraph?". On figures, we depict real edges of an s-graph with straight lines, and subdivisible edges with dashed lines.

Several  $\Pi_B$  problems of interest are studied in the litterature. For some of them, the existence of a polynomial time algorithm is trivial, but efforts are devoted toward optimized algorithms. For example, Alon, Yuster and Zwick solve  $\Pi_T$  in time  $O(m^{1.41})$  (instead of the obvious  $O(n^3)$  algorithm), where  $T$  is the s-graph depicted on Figure 1. This problem is known as *triangle detection*. Tarjan and Yannakakis [9] solve  $P_H$  in time  $O(n + m)$  where  $H$  is the s-graph depicted on Figure 1.

<sup>1</sup> Email: benjamin.leveque@g-scop.inpg.fr

<sup>2</sup> Email: dylin@Princeton.EDU

<sup>3</sup> Email: Frederic.Maffray@g-scop.inpg.fr

<sup>4</sup> Email: nicolas.trotignon@univ-paris1.fr

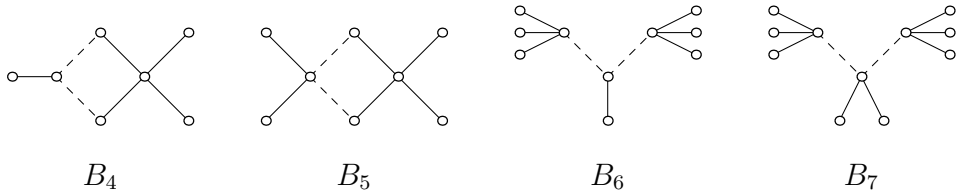


Fig. 3. Some s-graphs with pending edges

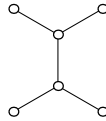


Fig. 4.  $I_1$

But for some  $\Pi_B$ 's, the existence of a polynomial time algorithm is non-trivial. A *pyramid* (resp. *prism*, *theta*) is any graph that is a realisation of the s-graph  $B_1$  (resp.  $B_2$ ,  $B_3$ ) depicted on figure 2. Chudnovsky and Seymour [5] gave an  $O(n^9)$ -time algorithm for  $\Pi_{B_1}$  (or equivalently, for detecting a pyramid). As far as we know, that is the first example of a solution to a  $\Pi_B$  whose complexity is non-trivial to settle. In contrast, Maffray and Trotignon [7] proved that  $\Pi_{B_2}$  (or detecting a prism) is NP-complete. Chudnovsky and Seymour [4] gave an  $O(n^{11})$ -time algorithm for  $P_{B_3}$  (or detecting a theta). Their algorithm relies on the solution of a problem called “three-in-a-tree”. Note that the algorithm for three-in-tree is quite general since it can be used to solve a lot of  $\Pi_B$  problems, including the detection of pyramids.

These facts are a motivation for a systematic study of  $\Pi_B$ . A further motivation is that very similar s-graphs can lead to a drastically different complexity. The following example is maybe more striking than pyramid/prism/theta :  $\Pi_{B_4}$ ,  $\Pi_{B_6}$  are polynomial and  $\Pi_{B_5}$ ,  $\Pi_{B_7}$  are NP-complete, where  $B_4, \dots, B_7$  are the s-graphs depicted on figure 3.

*Notation*

By  $C_k$  ( $k \geq 3$ ) we denote the cycle on  $k$  vertices, by  $K_l$  ( $l \geq 1$ ) the clique on  $l$  vertices. By  $I_l$  ( $l \geq 1$ ) we denote the tree on  $l + 5$  vertices that we obtain by taking a path of length  $l$  with end  $a, b$ , and by adding four vertices, two of them adjacent to  $a$ , the two others two  $b$ , see Figure 4. When a graph  $G$  contains a graph isomorphic to  $H$  as an induced subgraph, we will often say “ $G$  contain an  $H$ ”.

## 2 Detection of holes with prescribed vertices

Let  $\Delta(G)$  be the maximum degree of  $G$ . Let  $\mathcal{I}$  be a set of graphs and  $k$  be an integer. Let  $\Gamma_{\mathcal{I}}^k$  be the problem whose instance is  $(G, x, y)$  where  $G$  is a graph such that  $\Delta(G) \leq k$ , with no induced subgraph in  $\mathcal{I}$  and  $x, y \in V(G)$  are two non-adjacent vertices of degree 2. The question is "Does  $G$  contain a hole passing through  $x, y$  ?". For simplicity, we write  $\Gamma_{\mathcal{I}}$  instead of  $\Gamma_{\mathcal{I}}^{+\infty}$  (so, the graph in the instance of  $\Gamma_{\mathcal{I}}$  has unbounded degree). Also we write  $\Gamma^k$  instead of  $\Gamma_{\emptyset}^k$  (so the graph in the instance of  $\Gamma^k$  has no restriction on its induced subgraphs). Bienstock [3] proved that  $\Gamma = \Gamma_{\emptyset}$  is NP-complete. For  $I = \{K_3\}$  and  $I = \{K_{1,4}\}$ ,  $\Gamma_{\mathcal{I}}$  can be shown to be NP-complete, and a consequence is the NP-completeness of several problems of interest: see [7] and [8].

We try to settle  $\Gamma_{\mathcal{I}}^k$  for as many  $\mathcal{I}$ 's and  $k$ 's as we can because we need this in the proofs of the results in the next section. In particular, we give the complexity of  $\Gamma_{\mathcal{I}}$  when  $\mathcal{I}$  contains only one connected graph and of  $\Gamma^k$  for all  $k$ . We also settle  $\Gamma_{\mathcal{I}}^k$  for some cases when  $I$  is a set of cycles. The polynomial cases are either trivial, or are a direct consequence of the algorithm three-in-a-tree of Chudnovsky and Seymour that we have already mentioned. The NP-complete cases follow from several extensions of Bienstock's construction.

**Theorem 2.1** *Let  $H$  be a connected graph. Then either :*

- *$H$  is a path or a subdivision of a claw and  $\Gamma_{\{H\}}$  is polynomial.*
- *$H$  contains one of  $K_{1,4}, I_k$  for some  $k \geq 1$ , or  $C_l$  for some  $l \geq 3$  as an induced subgraph and  $\Gamma_{\{H\}}$  is NP-complete.*

Interestingly, a similar theorem has been proved by Alekseev:

**Theorem 2.2 (Alekseev, [1])** *Let  $H$  be a connected graph that is not a path nor a subdivided claw. Then the problem of finding a maximum stable set in  $H$ -free graphs is NP-hard.*

But the complexity of the maximum stable set problem is not known in general for  $H$ -free graphs when  $H$  is a path or a subdivided claw. See [6] for a survey.

**Theorem 2.3** *The following statements hold.*

- *For any  $k \in \mathbb{Z}$  with  $k \geq 2$ , the problem  $\Gamma^k$  is NP-complete when  $k \geq 3$  and polynomial when  $k = 2$ .*
- *If  $\mathcal{H}$  is any finite list of cycles  $C_{k_1}, C_{k_2}, \dots, C_{k_m}$  such that  $C_6 \notin \mathcal{H}$ , then  $\Gamma_{\mathcal{H}}^3$  is NP-complete.*

### 3 $\Pi_B$ for some special s-graphs

The s-graphs  $B_4, \dots, B_7$  are depicted on Figure 3.

**Theorem 3.1** *There is an  $O(n^{13})$ -time algorithm for  $\Pi_{B_4}$ , an  $O(n^{14})$ -time algorithm for  $\Pi_{B_6}$ , but  $\Pi_{B_5}$ ,  $\Pi_{B_7}$  are NP-complete.*

We put :  $sK_5 = (\{a, b, c, d, e\}, \emptyset, (\{a, b, c, d, e\}_2^{\{a, b, c, d, e\}}))$ . So  $sK_5$  is the s-graph on five vertices with all its edges subdivisible. The following theorem is the only NP-hardness result known for an s-graph with no real edges.

**Theorem 3.2**  $\Pi_{sK_5}$  is NP-complete.

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