

# *Granularity of models, choice of domains*

## *Examples and application*

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# Outline

1. Choice of domains, *granularity* of the model
2. Illustration on a *toy problem*
  - Pentaminoes
3. Illustration on a real application: multi-leaf sequencing
  - Direct model
  - Counter model
  - Path model
4. Stepping back, looking for a generic answer
  - Set variables
  - MDD consistency
5. Conclusion

# 1- Choice of domains

- Given a constraint  $C$  and a domain  $D$ 
  - Filtering = project the relation of  $C \cap D$  on the domain representation

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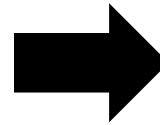
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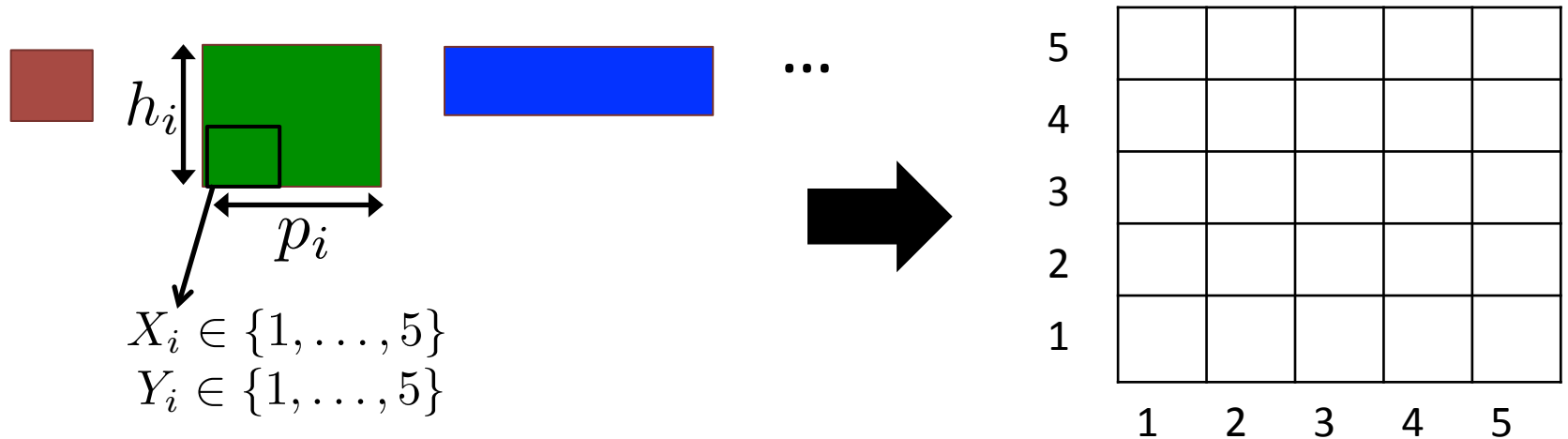


5					
4					
3					
2					
1					
	1	2	3	4	5

- Let's model a simple packing/placement problem

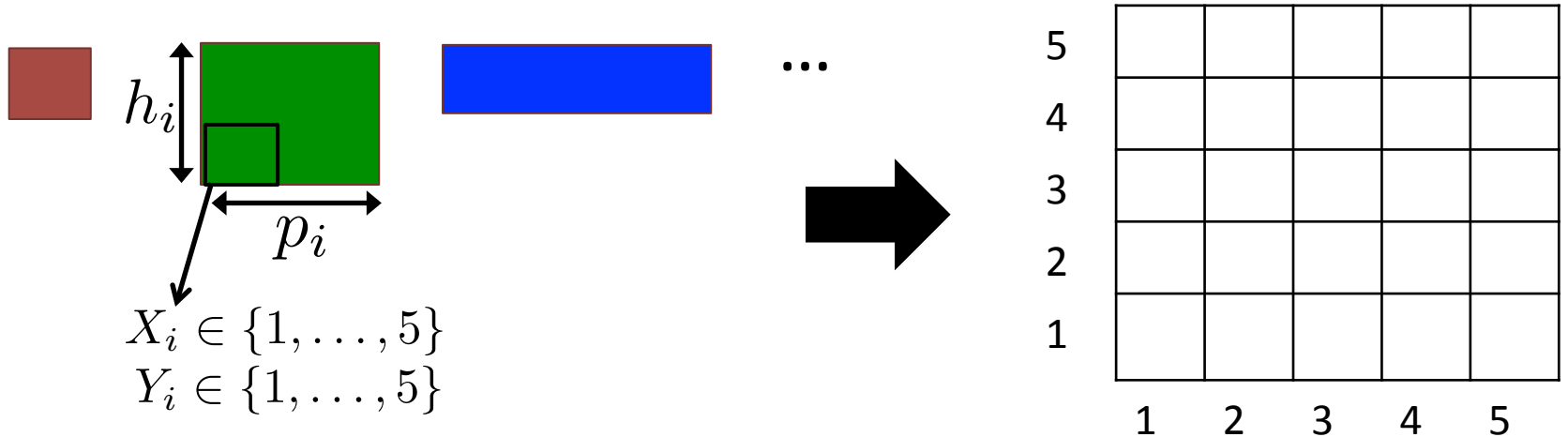
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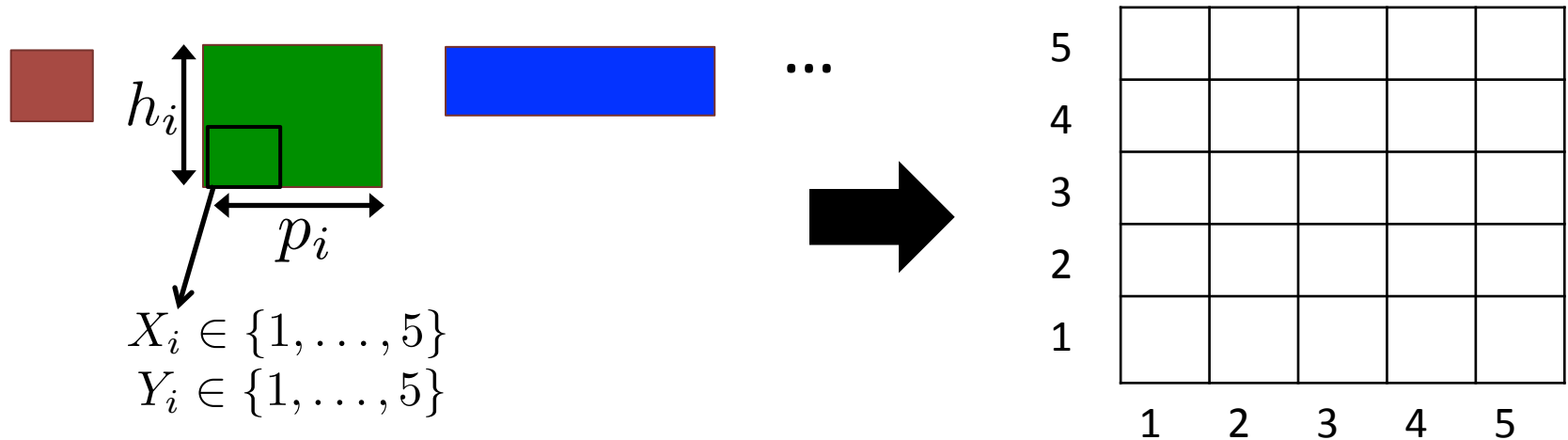


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i below j
i above j
i left of j
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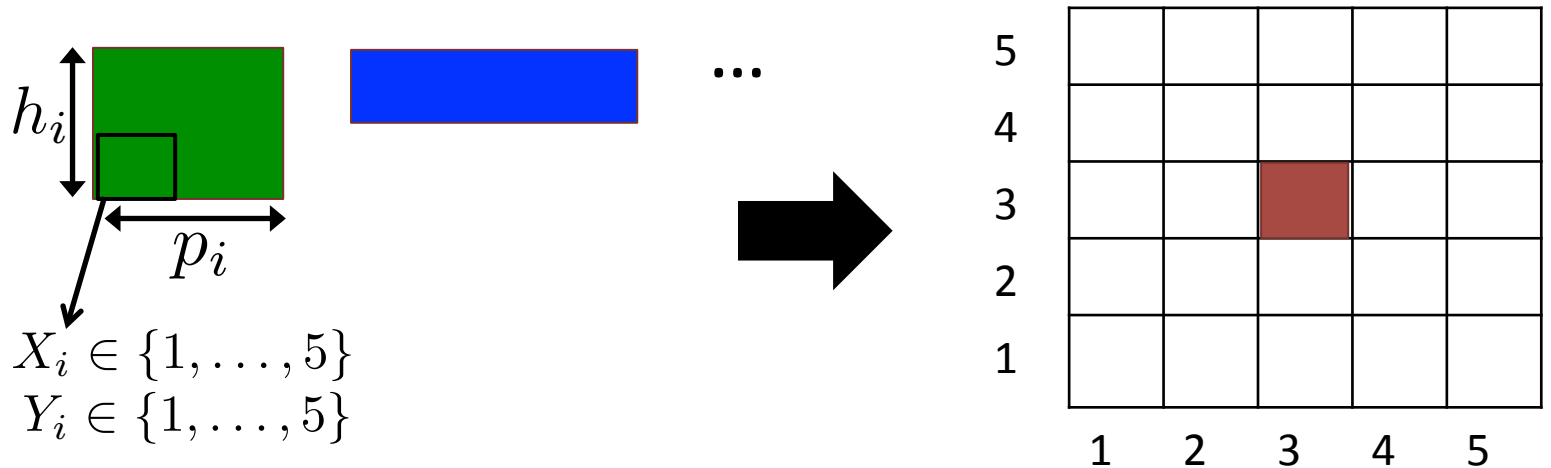
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**➔** GEOST



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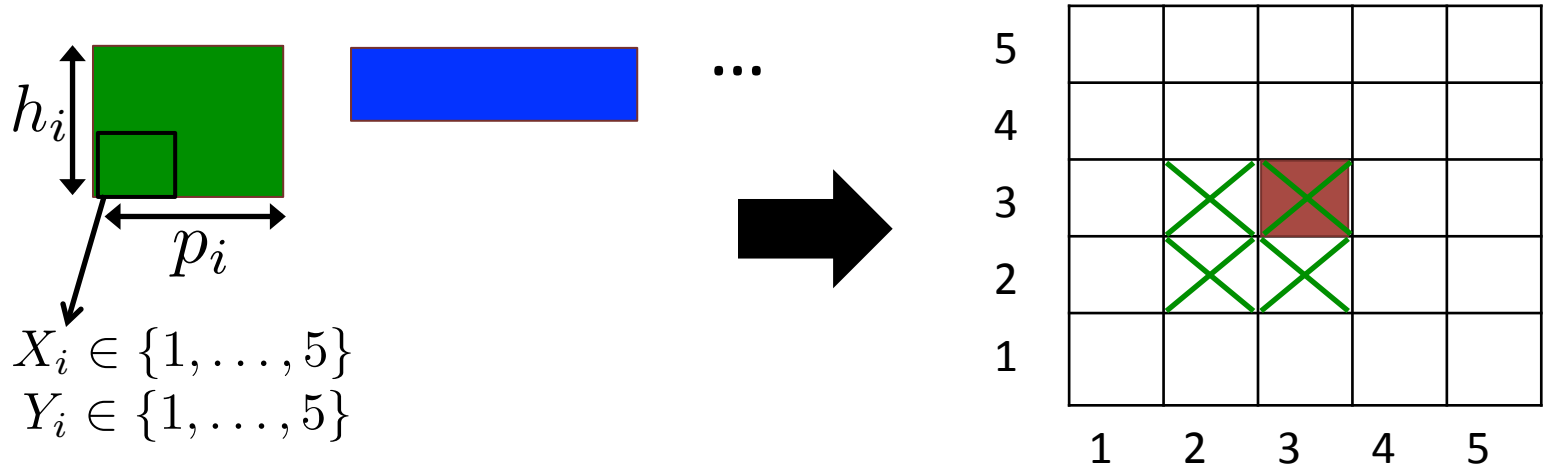
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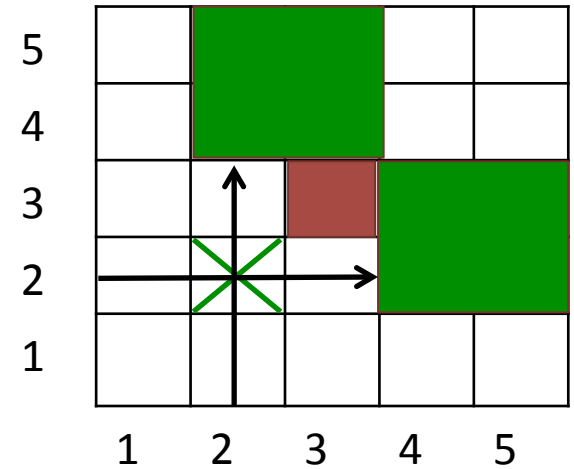
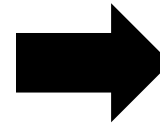
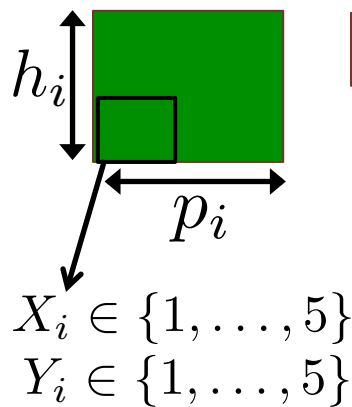
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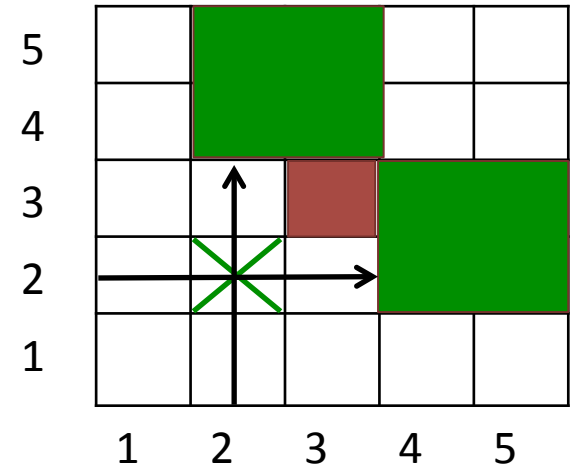
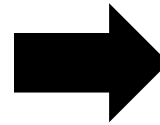
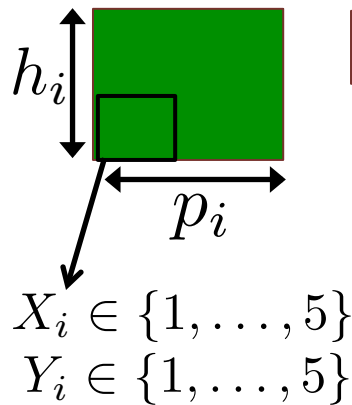
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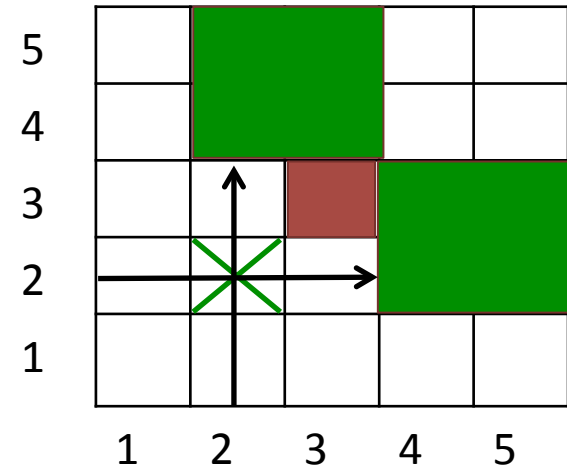
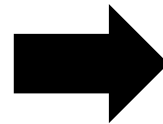
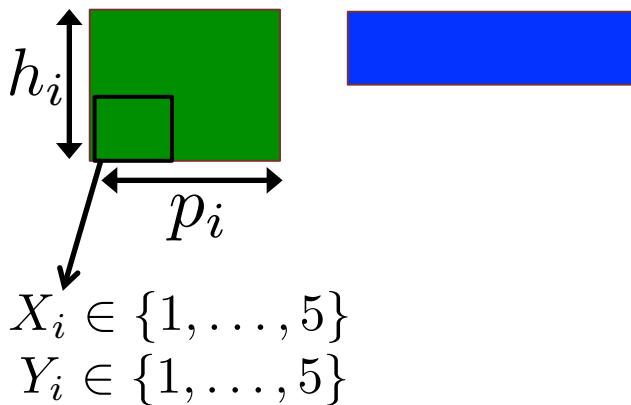
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- This reasoning can not be expressed in the domains
- GEOST probably knows it but can't communicate it to the rest of the model

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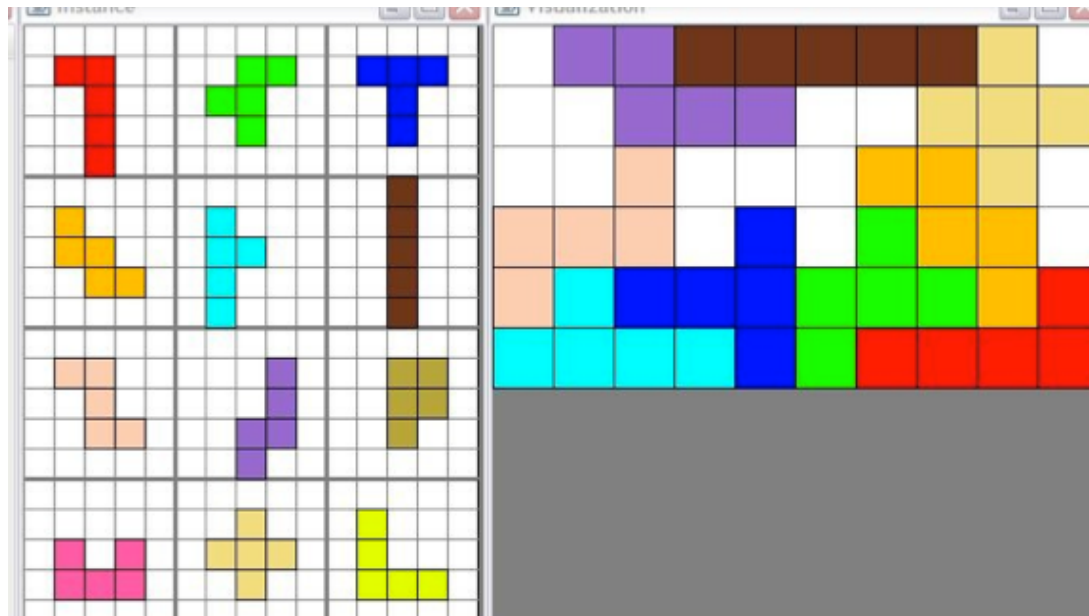
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  - Filtering = project the relation of  $C \cap D$  on the domain representation
- Choice of domains = choice of possible reasoning
- Question variables and domains to find out the proper *granularity* of information that should be represented
  - *A CP model reveals key combinatorial structures*
  - *Identify structures then decide variables-domains ?*

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## 2- Example of Pentaminoes

- *Modeling Irregular Shape placements problems with regular constraints*, Mikael Z. Lagerkvist, Gilles Pesant 2008.
- Example of Pentaminoes:



- All shapes you can create with five connected unit squares



## 2- Example of Pentaminoes

- Since shapes are irregular, “holes” might matter more.
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	$x_{22}$	$x_{23}$	

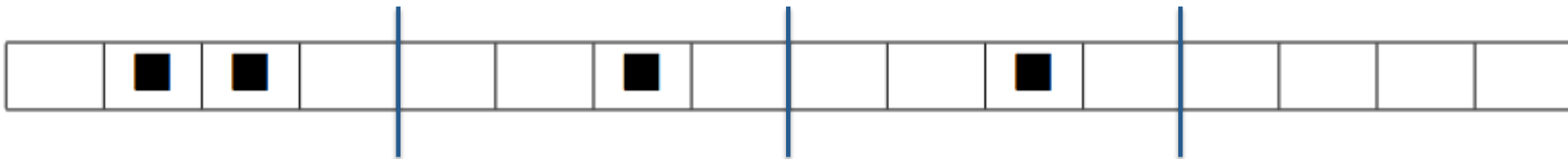
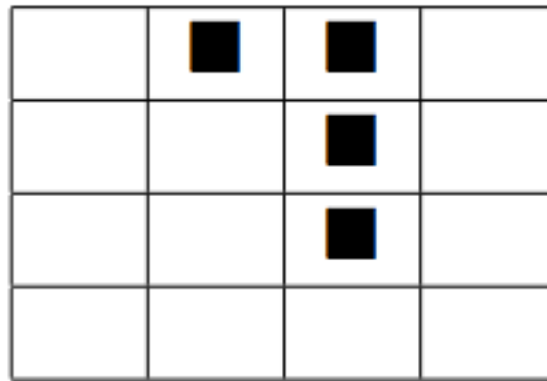
$$x_{ij} \in \{0, 1\}$$

	■	■	
		■	
		■	

0	1	1	0
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## 2- Example of Pentaminoes

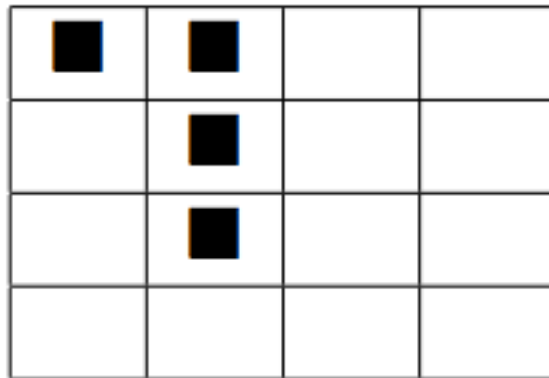
- How to state the placement of the shape ?
- Let's flatten the matrix:



A feasible sequence: 0110001000100000

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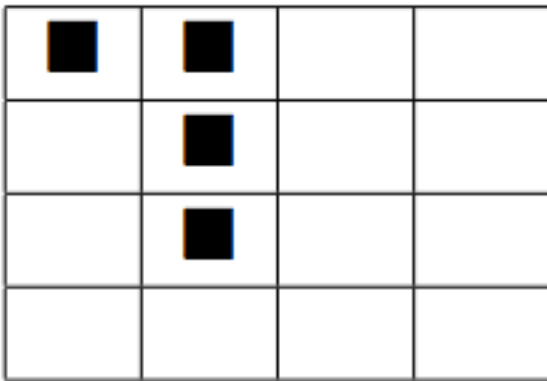
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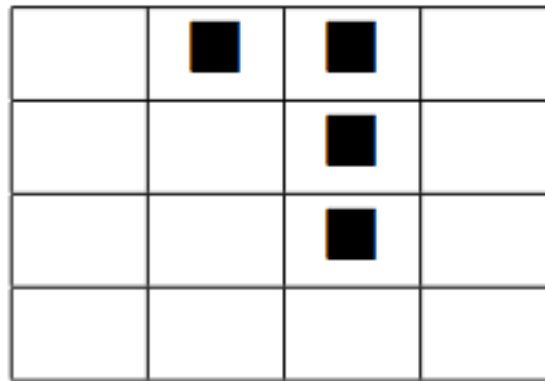
Another feasible sequence : 1100010001000000

## 2- Example of Pentaminoes

- How to state the placement of the shape ?



1100010001000000

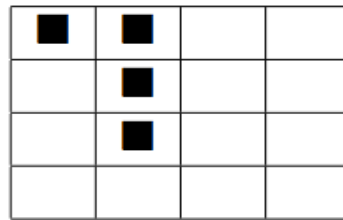


0110001000100000

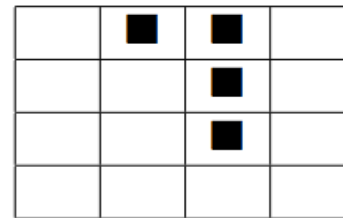
The sequences can be generalized to :  $0^* \underbrace{1100010001}_{} 0^*$

# 2- Example of Pentaminoes

- How to state the placement of the shape ?



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The sequences can be generalized to :  $0^*11000100010^*$

Use regular expressions and  
the Regular constraint:

$R$	$:=$	$RR$	concatenation
		$R^*$	repetition
		$R R$	alternation
		$(R)$	grouping
		$\epsilon$	empty string
		$X$	base values

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Problem: The expression  $0^*11000100010^*$  allows the following placement

			■
■			
■			
■			

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Solution: add extra column with forced zeroes



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Size	regular		geost	
	failures	time	failures	time
20 × 3	35 680	9 320	47 381	49 740
15 × 4	649 068	147 210	888 060	939 060
12 × 5	2 478 035	576 270	3 994 455	4 112 870
10 × 6	5 998 165	1 517 150	9 688 985	10 726 810

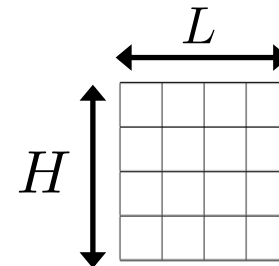
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Search for all solutions

More precise domains might allow to express more reasoning

## 2- Example of Pentaminoes

- *Modeling Irregular Shape placements problems with regular constraints*, Mikael Z. Lagerkvist, Gilles Pesant 2008.
- Express placement as regular constraints to capture “holes” in the placement leads to stronger propagation
- Drawback in the size of the model:  $n$  pentaminoes
  - Standard:  $O(n(L + H))$
  - Regular:  $O(n(L \times H))$



*Question the granularity of representation*

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# 3- The Multileaf Collimator Sequencing Problem

*Data* : A matrix of integers (**the intensities**)

*Question* : Find a decomposition into a weighted sum of Boolean matrices such that,

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B = 6

K = 3

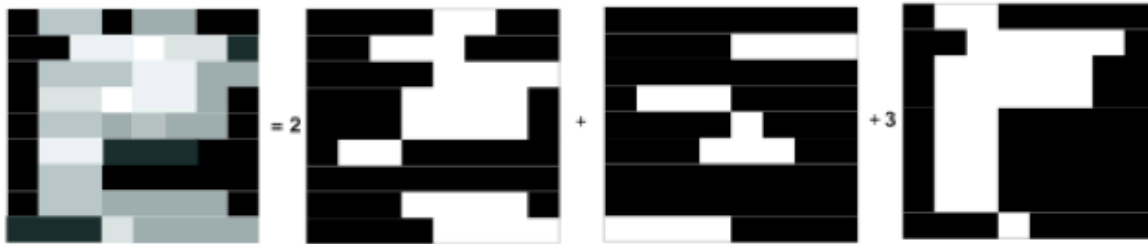


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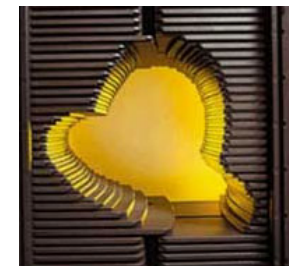
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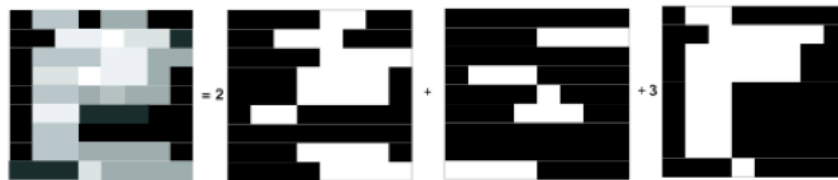
$$\text{minimise } w_1 K + w_2 B$$

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  - The sum of the coefficients (**Beam on time B**) is minimum
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- In fact  $B^*$  is easy to compute
  - Minimizing  $K$  alone is however NP-Hard and so is the weighted sum



*minimise  $w_1K + w_2B$*

$$\begin{bmatrix} 0 & 3 & 3 & 0 & 2 & 2 & 0 & 0 \\ 0 & 0 & 5 & 5 & 6 & 4 & 4 & 1 \\ 0 & 3 & 3 & 3 & 5 & 5 & 2 & 2 \\ 0 & 4 & 4 & 6 & 5 & 5 & 2 & 0 \\ 0 & 3 & 3 & 2 & 3 & 2 & 2 & 0 \\ 0 & 5 & 5 & 1 & 1 & 1 & 0 & 0 \\ 0 & 3 & 3 & 0 & 0 & 0 & 0 & 0 \\ 0 & 3 & 3 & 2 & 2 & 2 & 2 & 0 \\ 1 & 1 & 1 & 4 & 2 & 2 & 2 & 2 \end{bmatrix} = 2 \begin{bmatrix} 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 \end{bmatrix} + 3 \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 \end{bmatrix} + 3 \begin{bmatrix} 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \end{bmatrix}$$



### 3- The Direct model

- Not so easy to model
- Let's fix cardinality ( $K$ ) and Beam-on time ( $B^*$ ) and look for a feasible decomposition

$$\begin{bmatrix} 2 & 4 & 3 \\ 3 & 4 & 2 \end{bmatrix} = 2 \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} + 2 \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix} + 1 \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

*Variables :*  $\forall k \leq K$   $b_k \in \{1, \dots, M\}$   
 $\forall k \leq K, i \leq m, j \leq n,$   $x_{ij}^k \in \{0, 1\}$

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$x_{23}^2 = 0$

Variables :

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DM<sub>1</sub> :

$\sum_{k \leq K} b_k = B^*$

# 3- The Direct model

- Not so easy to model
- Let's fix cardinality (K) and Beam-on time (B\*) and look for a feasible decomposition

$$\begin{bmatrix} 2 & 4 & 3 \\ 3 & 4 & 2 \end{bmatrix} = \overset{b_1 = 2}{\uparrow} \textcircled{2} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} + \overset{b_2 = 2}{\uparrow} \textcircled{2} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 0 \end{bmatrix} + \overset{b_3 = 1}{\uparrow} \textcircled{1} \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

$x_{23}^2 = 0$

Variables :  $\forall k \leq K$   
 $\forall k \leq K, i \leq m, j \leq n,$

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$\sum_{k \leq K} b_k \times x_{ij}^k = I_{ij}$

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CONSECUTIVEONES( $\{x_{i1}^k, \dots, x_{in}^k\}$ )

DM<sub>4</sub> :  $\forall i \leq m, j \leq n$

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$$\begin{aligned} DM_1 : & & \sum_{k \leq K} b_k & = B^* \\ DM_2 : & & b_1 \geq b_2 \geq \dots \geq b_K & \\ DM_3 : & \forall k \leq K, i \leq m, & \text{REGULAR}([x_{i1}^k, \dots, x_{in}^k], A(0^*1^*0^*)) & \\ DM_4 : & \forall i \leq m, j \leq n & \sum_{k \leq K} b_k \times x_{ij}^k & = I_{ij} \end{aligned}$$

- Note: Some symmetries remain

$$2 \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} + 2 \begin{pmatrix} 0 & 1 & 0 \\ 0 & 1 & 0 \end{pmatrix} = 2 \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \end{pmatrix} + 2 \begin{pmatrix} 0 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix}$$



### 3- The Counter model

- Let's minimize the cardinality (K)

*minimise*  $K$   
*Variables:*  $\forall b \leq M \quad N_b \in \{0, \dots, B^*\}$   
 $\forall i \leq m, j \leq n, b \leq M \quad Q_{ij}^b \in \{0, \dots, M\}$

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$CM_1 : \quad \forall i \leq m, j \leq n \quad \sum_{b=1}^M b \times Q_{ij}^b = I_{ij}$   
 $CM_2 : \quad \sum_{b=1}^M b \times N_b = B^*$   
 $CM_3 : \quad \sum_{b=1}^M N_b = K$

$$\begin{bmatrix} 2 & 4 & 3 \\ 3 & 4 & 2 \end{bmatrix} = 2 \overset{Q^2}{\begin{bmatrix} 1 & 2 & 1 \\ 1 & 2 & 1 \end{bmatrix}} + 1 \overset{Q^1}{\begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}}$$

- How to express the consecutive one property on Q ?

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$CM_4 :$   $\forall b \leq M, i \leq m, \text{SUMOFINCREMENTS}(\{Q_{i1}^b, \dots, Q_{in}^b\}, N_b)$

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- How to express the consecutive one property on Q ?

$$\sum_{j=0}^{n-1} \max(Q_{i,j+1}^b - Q_{i,j}^b, 0) \leq N_b$$

## 3- The shortest path model

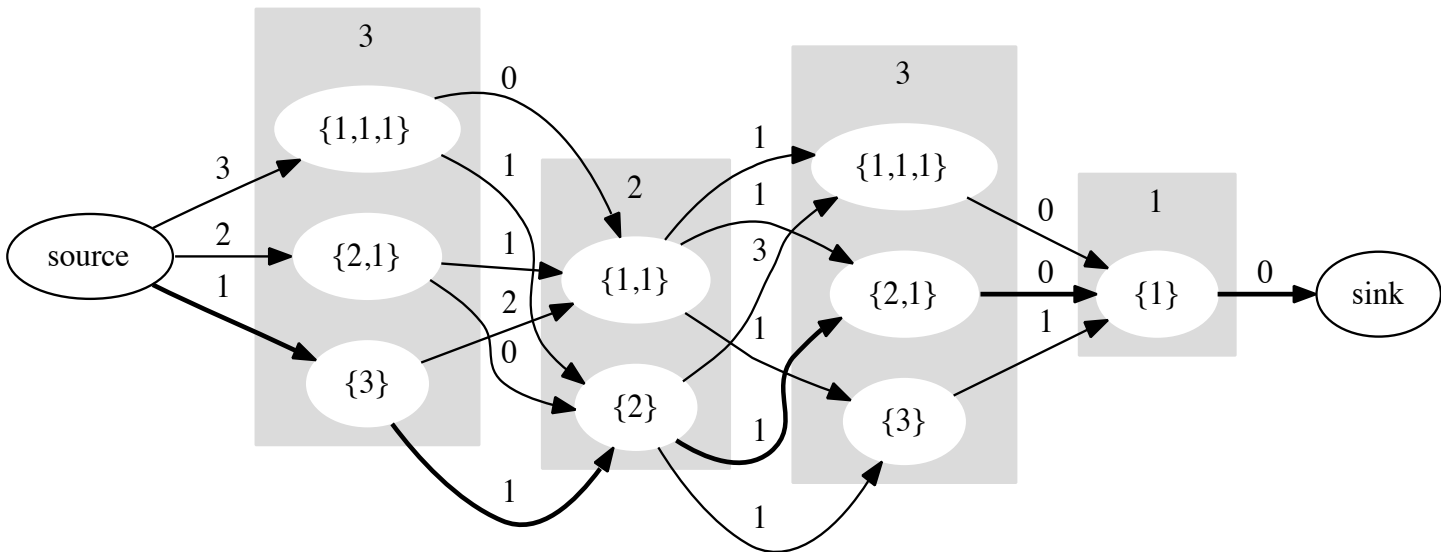
- Problem restricted to one row:  $[3,2,3,1]$

$$[3,2,3,1] = 2[1,0,0,0] + 1[1,1,0,0] + 1[0,1,1,1] + 2[0,0,1,0]$$

- The decomposition contains an integer partition of each element:
  - 3 is decomposed with  $\{2,1\}$
  - 2 with  $\{1,1\}$
  - 3 with  $\{2,1\}$
  - 1 with  $\{1\}$

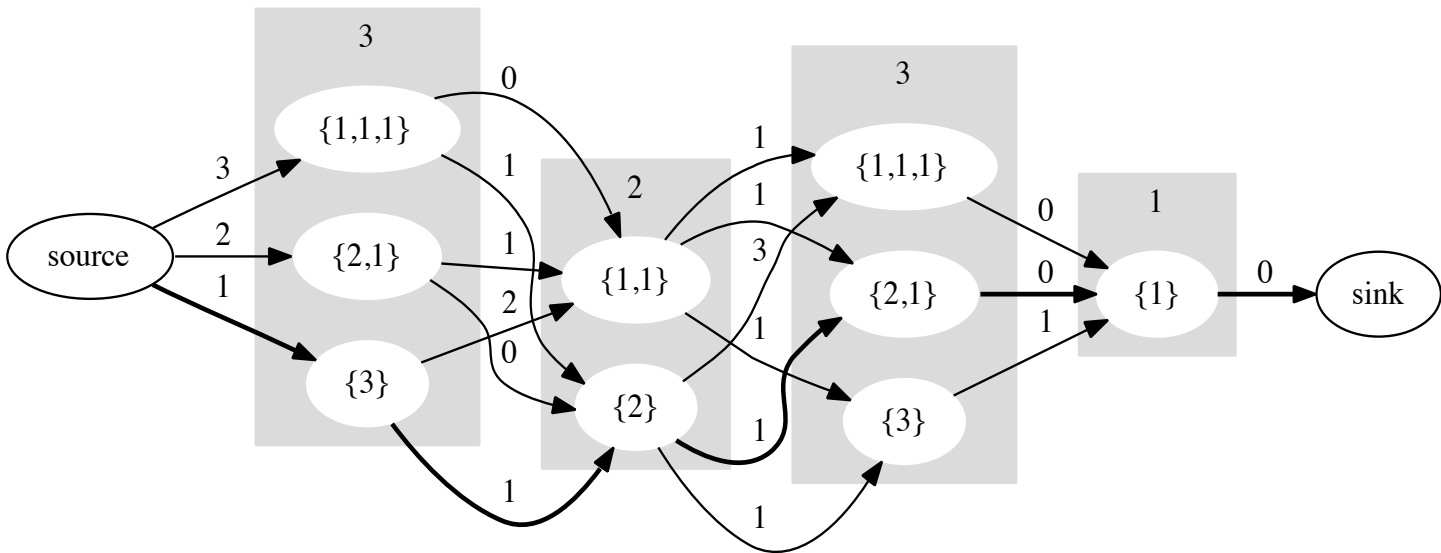
# 3- The shortest path model

- Minimisation of the cardinality for a single line : [3,2,3,1]
- Explicit representation of the integer partitions



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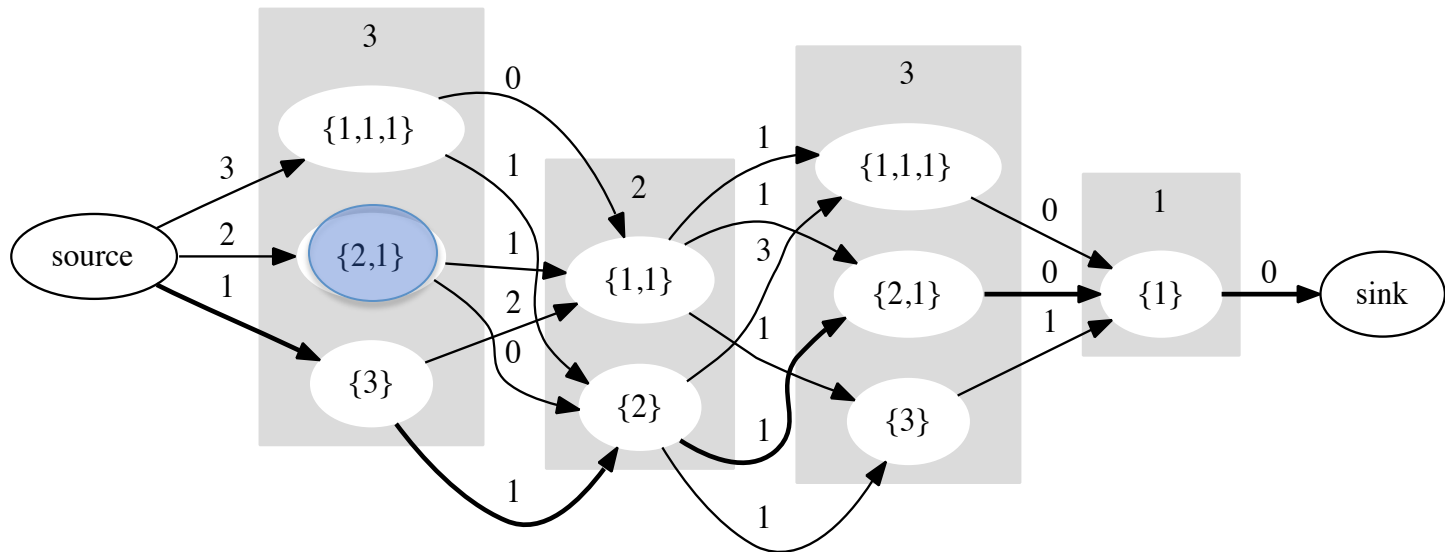


[3,2,3,1] =



# 3- The shortest path model

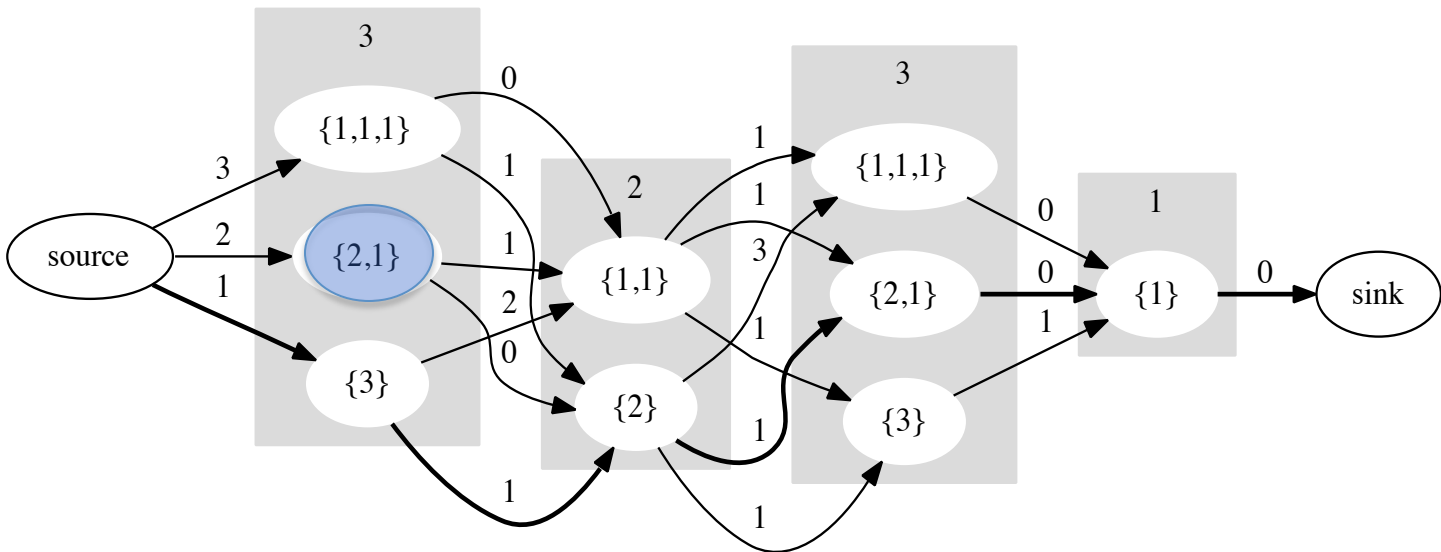
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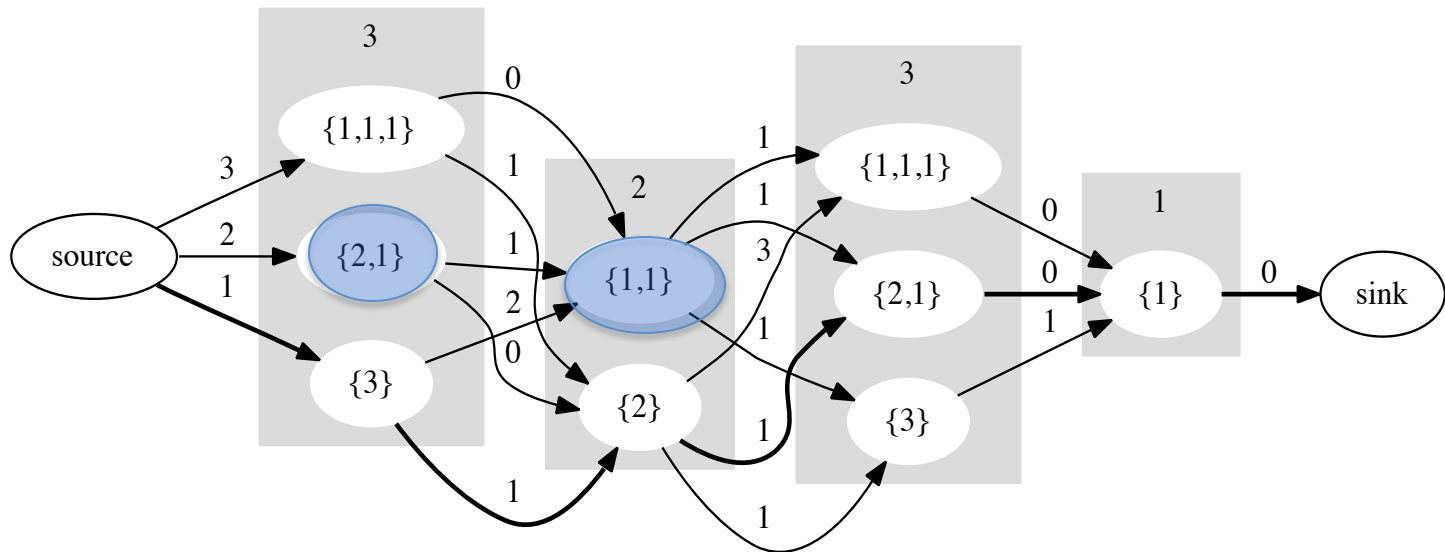
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$$[3,2,3,1] = 2[1,?, ?, ?] + 1[1,?, ?, ?]$$

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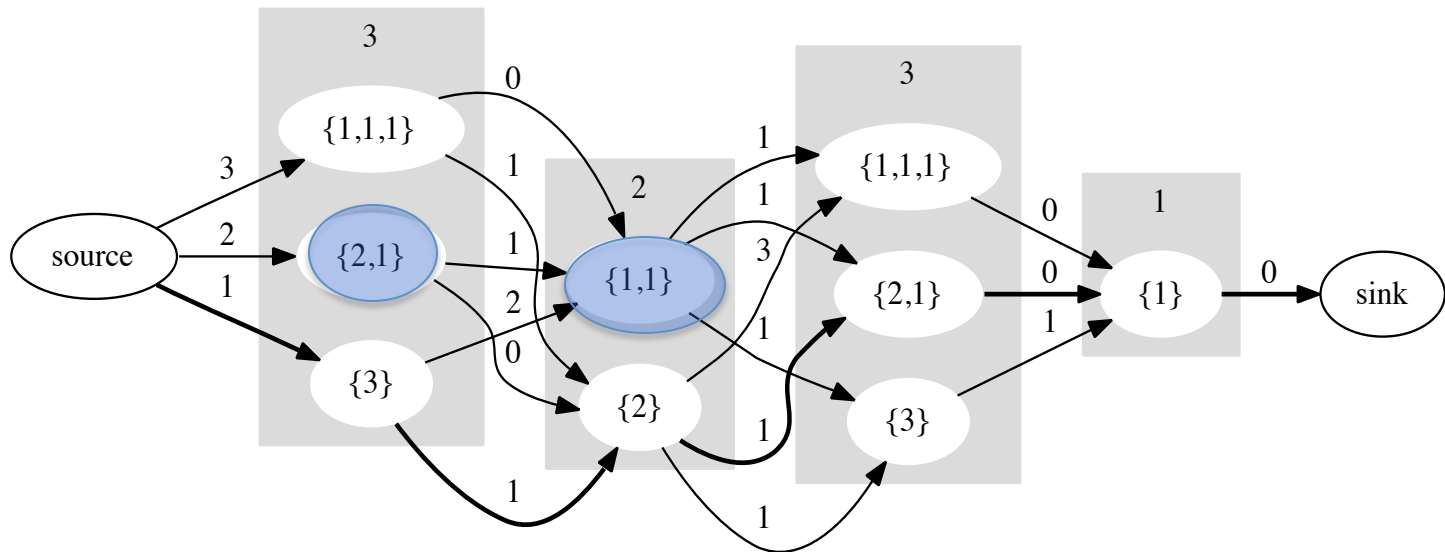
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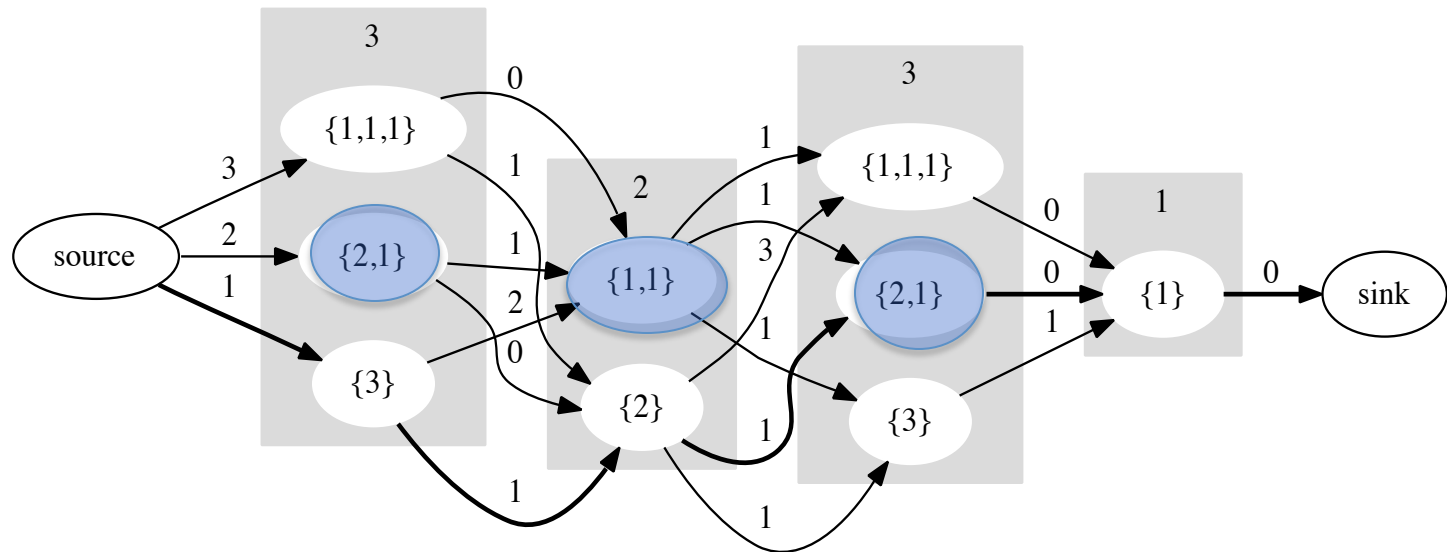


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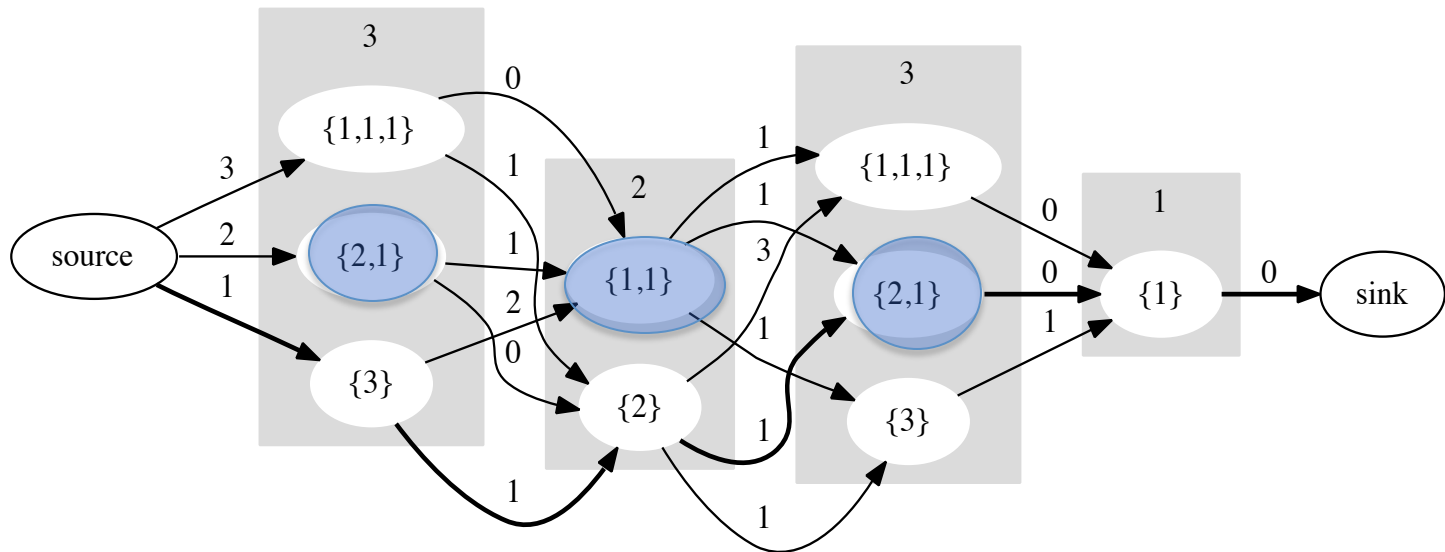


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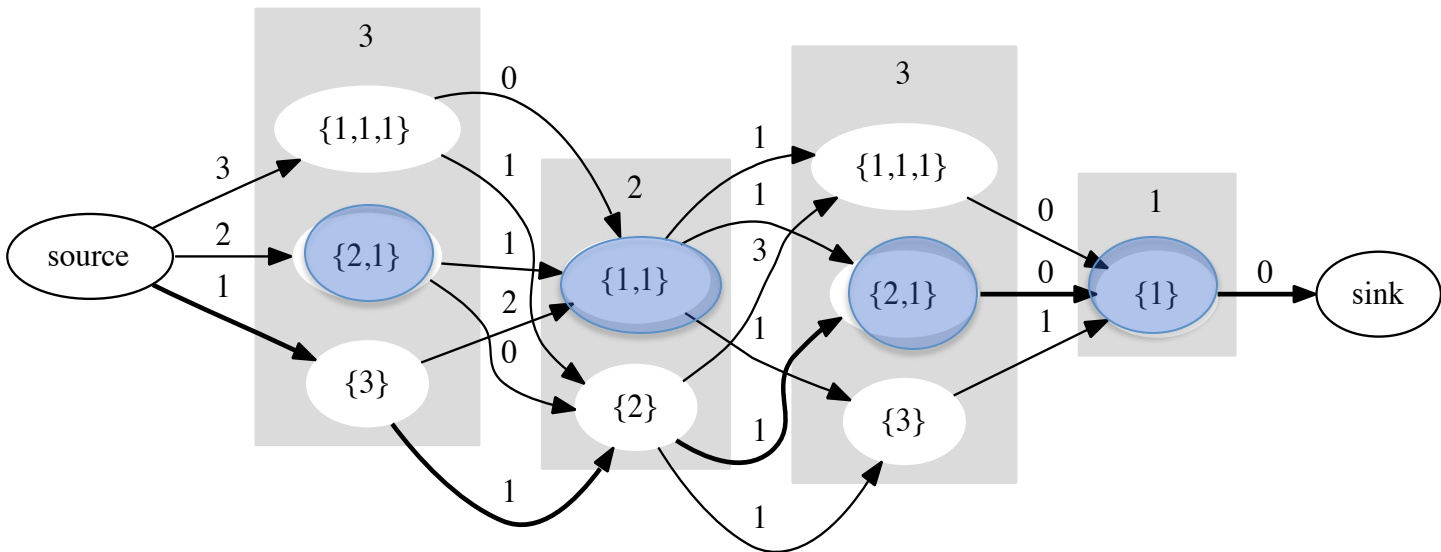
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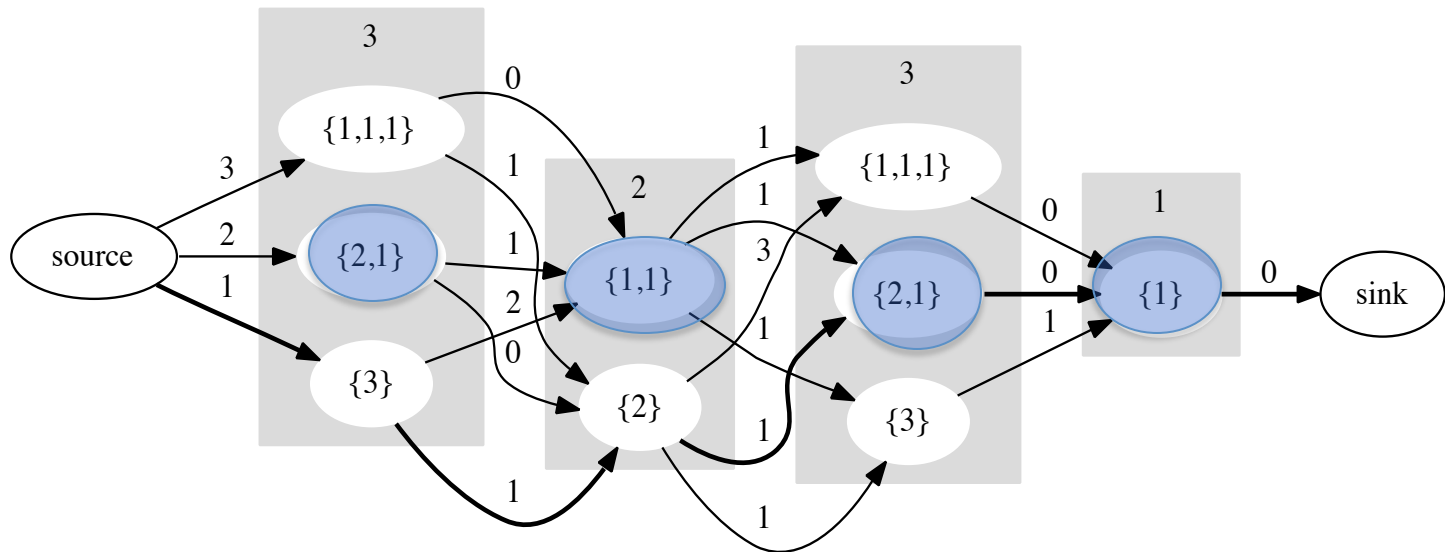
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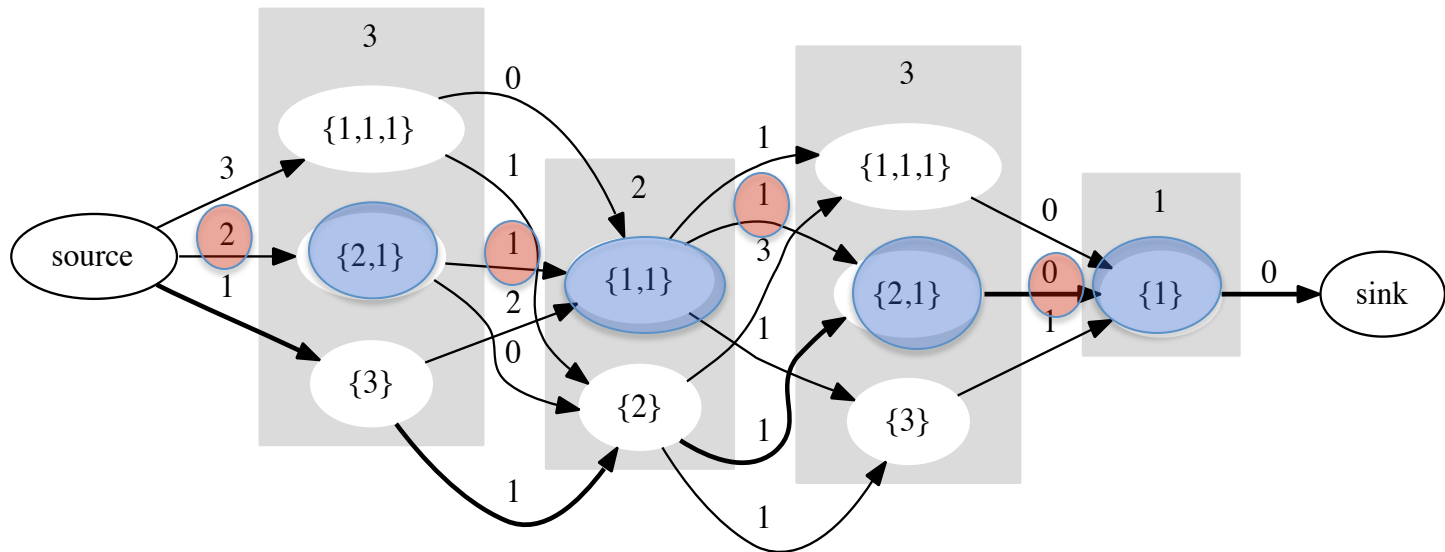
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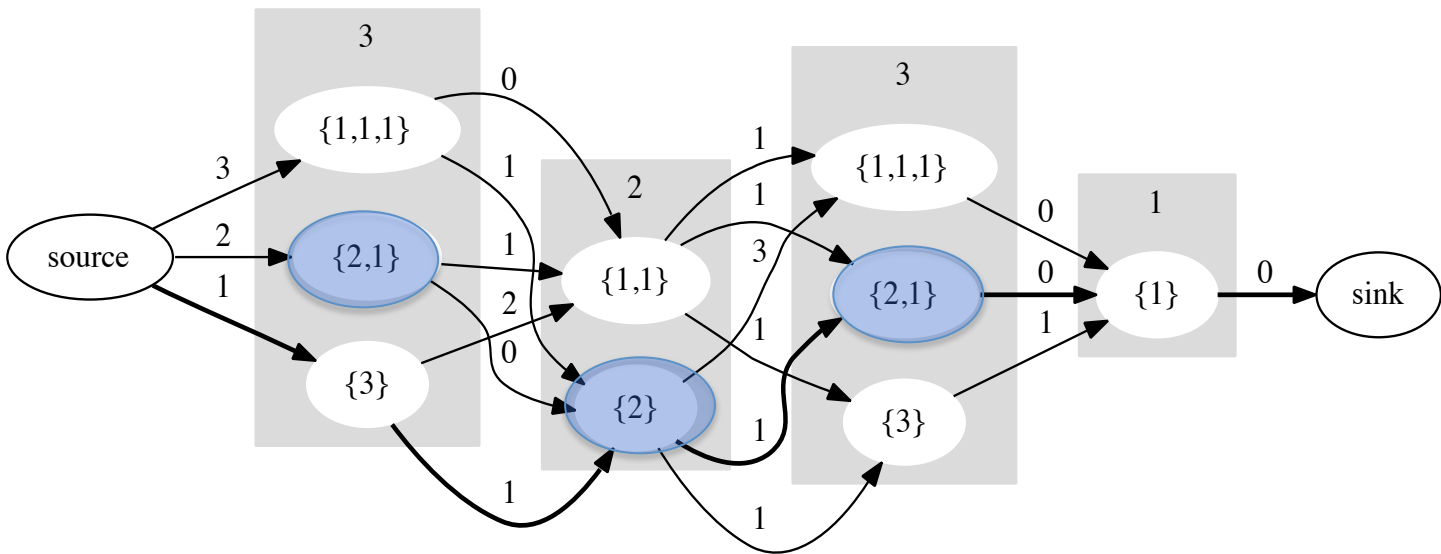
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$$\text{Cardinality } K = 2 + 1 + 1 + 0 = 4$$

# 3- The shortest path model

- A path encodes a decomposition
- The length of the path gives the cardinality

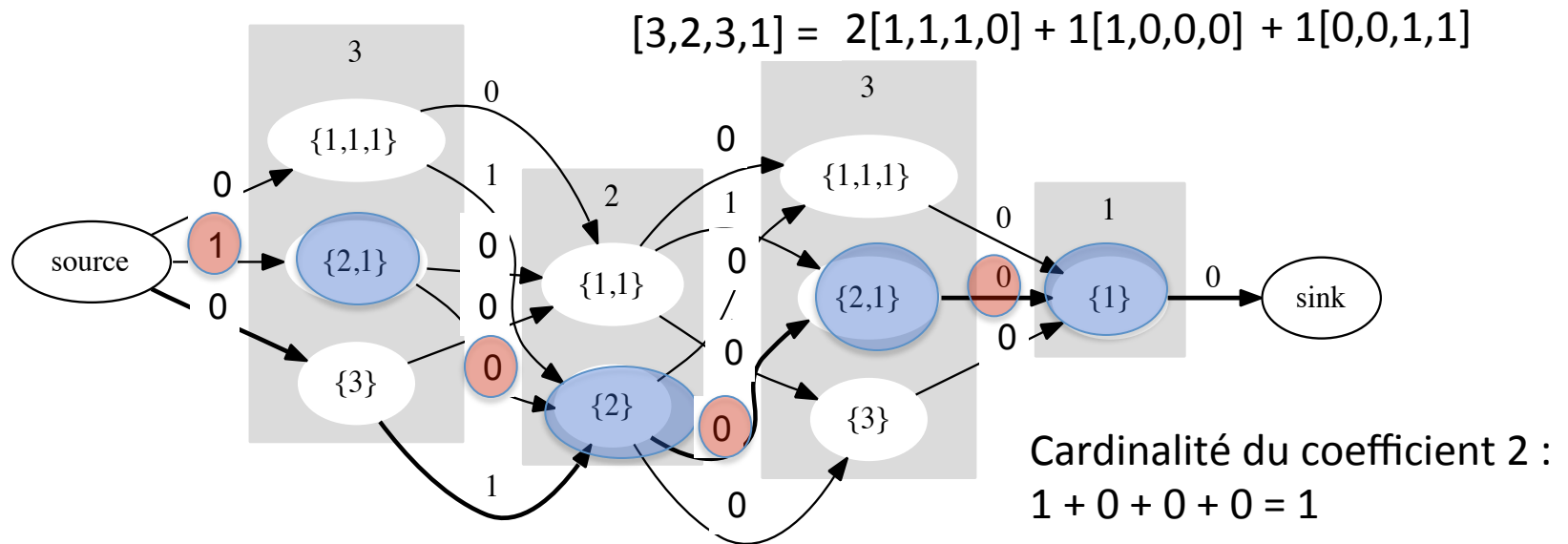


➔ A shortest path gives a minimum cardinality decomposition

$$[3,2,3,1] = 2[1,1,1,0] + 1[1,0,0,0] + 1[0,0,1,1] \quad K = 3$$

# 3- The shortest path model

- Costs can be restricted to a particular coefficient:



- Idea: it allows to maintain the minimum number of coefficient « 2 » needed for consecutive ones decomposition

### 3- The shortest path model

- Representations of the integer partition

- Example with intensity  $I = 10$  :

$$P \in \{\{10\}, \{9, 1\}, \{8, 2\}, \{8, 1, 1\}, \dots, \{4, 4, 2\}, \dots\}$$

- Occurrence representation:

*[Baatar, Boland, Brand, Stuckey CPAIOR'07 / Constraint 2011]*

$$Q_{10} = \{0, 1\}, Q_9 = \{0, 1\}, \dots, Q_4 = \{0, 1, 2\}, \dots, Q_1 = \{0, \dots, 10\}$$

$$P = \{4, 4, 2\} \quad \Leftrightarrow \quad Q_4 = 2, Q_2 = 1$$

- The filtering of the value  $\{4,4,2\}$  from the domain of  $P$  can not be expressed on  $Q$

### 3- The shortest path model

$minimise \quad w_1K + w_2B \quad \text{with}$

$\forall b \leq M$	$K \in \{0, \dots, nmM\}, B \in \{B^*, \dots, nmM\}$
$\forall i \leq m, j \leq n,$	$N_b \in \{0, \dots, nmM\}$
	$P_{ij} \in \{1, \dots,  P(I_{ij}) \}$ Partition variables

$CP_1 :$		$\sum_{b=1}^M b \times N_b = B$
$CP_2 :$		$\sum_{b=1}^M N_b = K$
$CP_3 :$	$\forall i \leq m,$	$\left\{ \begin{array}{l} \text{SHORTESTPATH}(G_1(i), \{P_{i1}, \dots, P_{in}\}, K) \\ \text{SHORTESTPATH}(G_2(i, b), \{P_{i1}, \dots, P_{in}\}, N_b) \\ \text{SHORTESTPATH}(G_3(i), \{P_{i1}, \dots, P_{in}\}, B) \end{array} \right.$
$CP_4 :$	$\forall i \leq m, b \leq M$	
$CP_5 :$	$\forall i \leq m,$	
$CP_6 :$	$\forall i \leq m, \forall j < m \text{ s.t } I_{ij} = I_{i,j+1}$	$P_{ij} = P_{i,j+1}$

- Shortest Path with M+2 resource constraints (the graph is identical for all constraints)

# Synthesis

- Size of the models for a given  $K$  and **maximum intensity  $M$** 
  - Direct model :  $O(KM + 2nmK)$
  - Counter model :  $O(MB^* + nmM^2)$
  - Path model : exponential in  $M$
- The level of consistency increases in each model
- More fine-grained domains allow for more reasoning
- Similar idea in MIP: column generation
  - An exponential number of variables can lead to a very strong linear relaxation

# Overview of results

- Some results using **CP**:
  - Counter model: 20 x 20 with max intensity 10 [Baatar, Boland, Brand, Stuckey 07], [Brand 08]
  - Path model: 40 x 40 with max intensity 10 [Cambazard, O'Mahony, O'Sullivan 09]
- **Dedicated algorithm**:
  - 15 x 15 with max intensity 10 (up to 10h of computation) [Kalinowski 08]
- Using **Benders decomposition**: [Taskin, Smith, Romeijn, Dempsey ANOR'09]  
Clinical instances (around 20x20 with max intensity 20) solved optimally with up to 5.8 h of computation
- Results can be improved using **Lagrangian Relaxation** when intensity is small  
[Cambazard, O'Mahony, O'Sullivan, 2010]
- Significant improvement using **Branch and Price and constraint propagation** :
  - 80 x 80 with max intensity 10 [Cambazard, O'Mahony, O'Sullivan, 2012]
  - 20 x 20 with max intensity 20
  - 12 x 12 with max intensity 25
  - Clinical instances with up to 10 min of computation



*Question the granularity of representation*

# Outline

1. Choice of domains, *granularity* of the model
2. Illustration on a *toy problem*
  - Pentaminoes
3. Illustration on a real application: multi-leaf sequencing
  - Direct model
  - Counter model
  - Path model
4. Stepping back, looking for a generic answer
  - Set variables
  - MDD consistency
5. Conclusion



# 4- Stepping back, looking for a generic answer

## *Set Variables*

- Set Variables [Puget, 1992], [Gervet, 1997]
  - Domain is set of sets  $D(X) = \{S \mid S \subseteq \{1, 2, 3, 4, 5, 6, 7, 8, 9\}\}$
  - A value is a set  $X = \{1, 4, 9\}$

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  - A value is a set  $X = \{1, 4, 9\}$
  - A representation with a lower/upper *bound*:  $D(X) = \{S \mid \underline{X} \subseteq S \subseteq \overline{X}\}$

Elements that can still go in the set:  $\overline{X} \subseteq \{1, 2, 4, 6, 9\}$

Elements that are in the set:  $\underline{X} \subseteq \{4, 9\}$

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Elements that are in the set:  $\underline{X} \subseteq \{4, 9\}$

- Equivalent to boolean variables:
$$b_1, b_2, b_6 \in \{0, 1\}$$
$$b_4 = 1, b_9 = 1$$
$$b_3 = 0, b_5 = 0, b_7 = 0, b_8 = 0$$

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- Common solver representation adds the cardinality:

$$\overline{X} \subseteq \{1, 2, 4, 6, 9\} \quad \underline{X} \subseteq \{4, 9\} \quad K = |X|$$

- Some reasoning on K can not be expressed on  $\underline{X}$  and  $\overline{X}$  alone

# 4- Stepping back, looking for a generic answer

## *Set Variables*

- Length-Lex representation [Gervet and Van-Hentenryck, 2006]
  - Order the sets by cardinality and lexicographically

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# 4- Stepping back, looking for a generic answer

*MDD-consistency*

## Limit : “constraints communicate through domains”

- All structural relationships among variables are projected onto the domains
- Potential solution space implicitly defined by Cartesian product of variable domains
- How to communicate more information between constraints ?
  - Multi-valued Decision Diagram MDD consistency  
[Hooker, Hadzic, Van Hove, 2007]
  - Explicit representation of more refined potential solution space
  - Limited width defines **relaxation MDD**

(From Willem-Jan Tutorial)

# 4- Stepping back, looking for a generic answer

## *MDD-consistency*

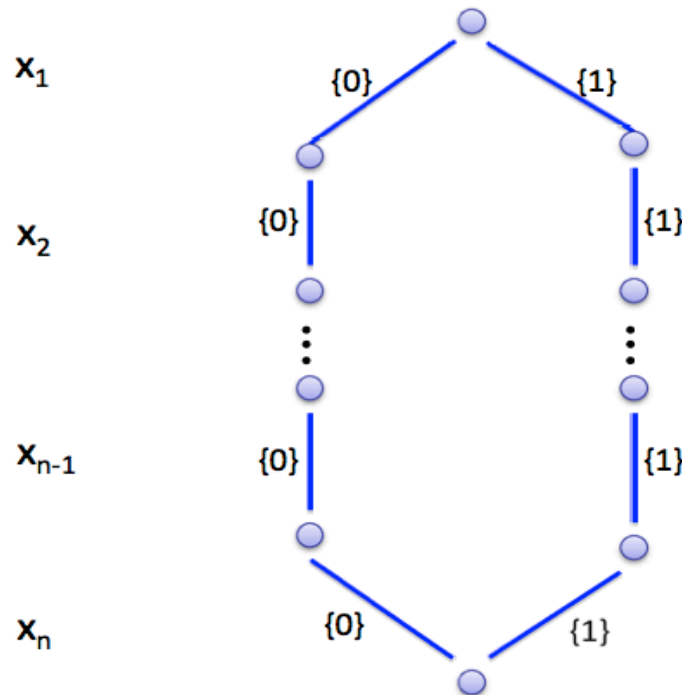
Limit : “constraints communicate through domains”

$AllEqual(x_1, x_2, \dots, x_n)$ , all  $x_i$  binary

$$x_1 + x_2 + \dots + x_n \geq n/2$$



domain representation, size  $2^n$



MDD representation, size 2

# Outline

1. Choice of domains, *granularity* of the model
2. Illustration on a *toy problem*
  - Pentaminoes
3. Illustration on a real application: multi-leaf sequencing
  - Direct model
  - Counter model
  - Path model
4. Stepping back, looking for a generic answer
  - Set variables
  - MDD consistency
5. Conclusion

# Conclusion

- A CP model reveals combinatorial structures of the problem:
  - TPP (p-median, hitting-set, k-TSP)
  - Matrix decomposition (shortest path with resource constraints)
- Find out the proper *granularity* where key-reasoning can be expressed
  - Find-out what the problem is made of (what structures) and only then, choose the variables/domains
- Modeling the objective function is often neglected
  - Relatively generic mechanisms that do not require an LP solver exist to reason about costs: Lagrangian Relaxation