

Constraint Programming

Global constraints

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(ROSP)

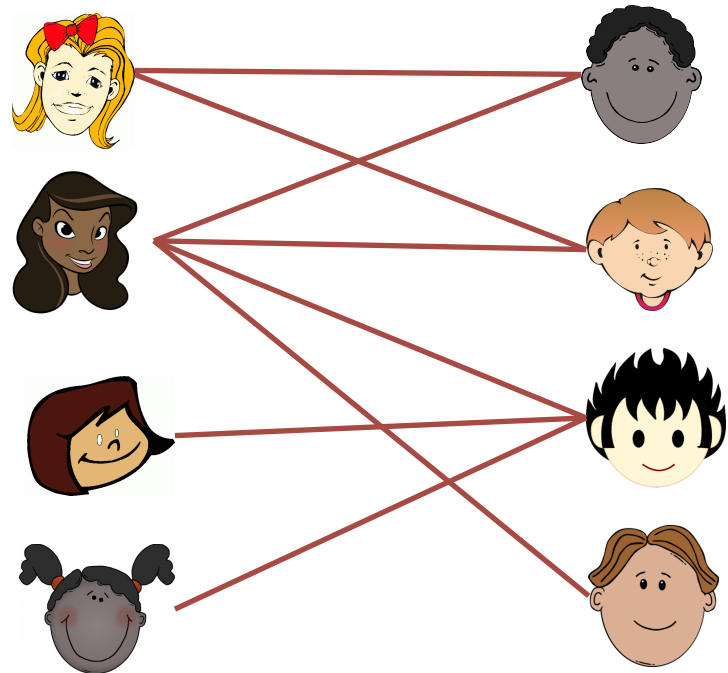
AllDifferent

- Hall's Marriage theorem (Hall, 1935):

(formulated as "Marriage theorem" by H. Weyl, 49)

*"If a group of men and women marry only if they have been introduced to each other previously, then a complete set of marriages is possible **if and only if every subset of men** has collectively been introduced to **at least as many women, and vice versa.**"*

Can they all get married ?



AllDifferent

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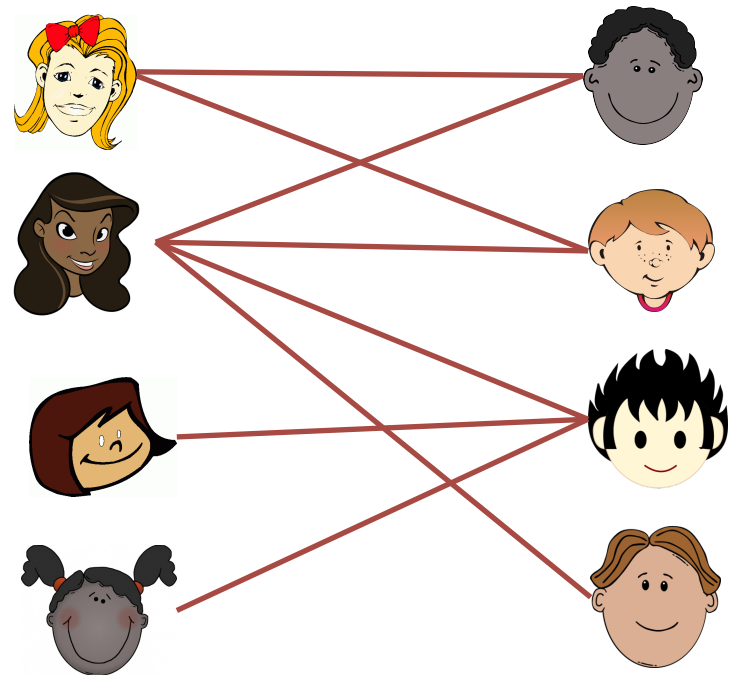
Can they all get married ?

Women = variables

Men = values

$$D(\text{👩}) = \{\text{👨}, \text{👦}\}$$

$$\text{AllDifferent}(\text{👩}, \text{👩}, \text{👧}, \text{👩})$$



AllDifferent

Tradeoff between level of consistency and complexity

Generalized Arc consistency	Régin, 94	$\mathcal{O}(n^{\frac{3}{2}} d)$
Range Consistency	Leconte, 96	$\mathcal{O}(n^2)$
Bounds Consistency	Puget, 98	$\mathcal{O}(n \log(n))$
Bounds Consistency	Mehlhorn et al, 2000	$\mathcal{O}(n)$
Bounds Consistency	Quimper et al, 2003	$\mathcal{O}(n)$

- Applications for GAC: timetabling, combinatorial design, sometimes scheduling, ...
- Most of the time BC is great (and much better than the decomposition)

Global cardinality

$$\text{GCC}(X = [x_1, \dots, x_n], [l_1, \dots, l_m], [u_1, \dots, u_m])$$

$$x_1 \in \{2\}, x_2 \in \{1, 2\}, x_3 \in \{2, 3\}, x_4 \in \{2, 3\}, x_5 \in \{1, 2, 3, 4\}, x_6 \in \{3, 4\}$$

$$\text{GCC}(X = \{x_1, x_2, x_3, x_4, x_5, x_6\}, [0, 1, 1, 2], [3, 2, 1, 3])$$

	1	2	3	4
l_j	0	1	1	2
u_j	3	2	1	3

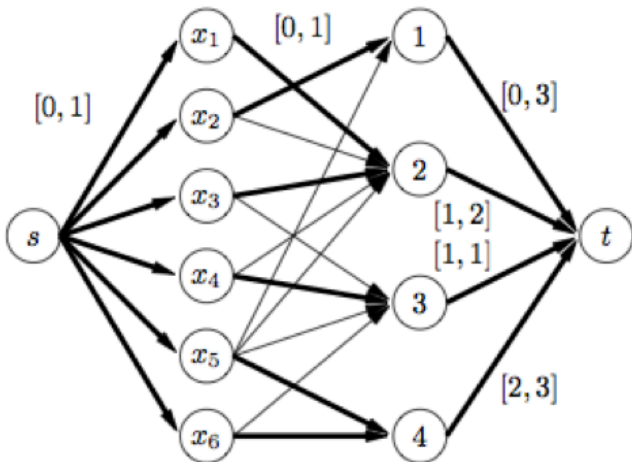
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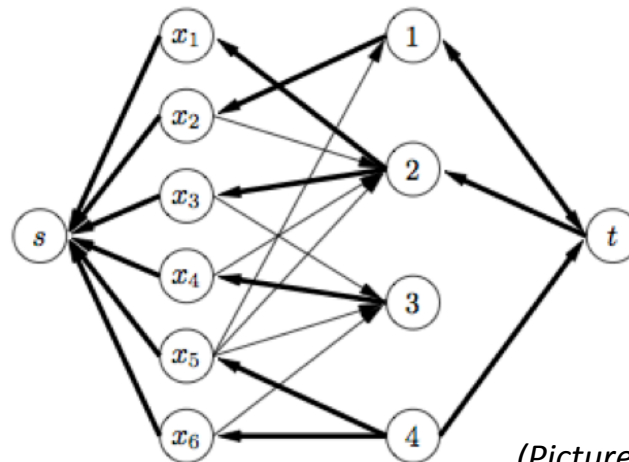
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a

The value network



b

The residual graph

(Picture from Claude-Guy Quimper's phd)

Bin-Packing

$\text{BINPACKING}([x_1, \dots, x_n], [l_1, \dots, l_m], [w_1, \dots, w_n])$

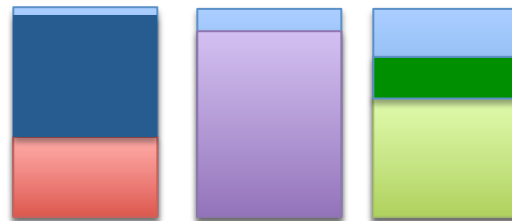
Variables:

x : items (domain is the possible bins)

l : the loads of the bins

Constants:

w : the size of the items



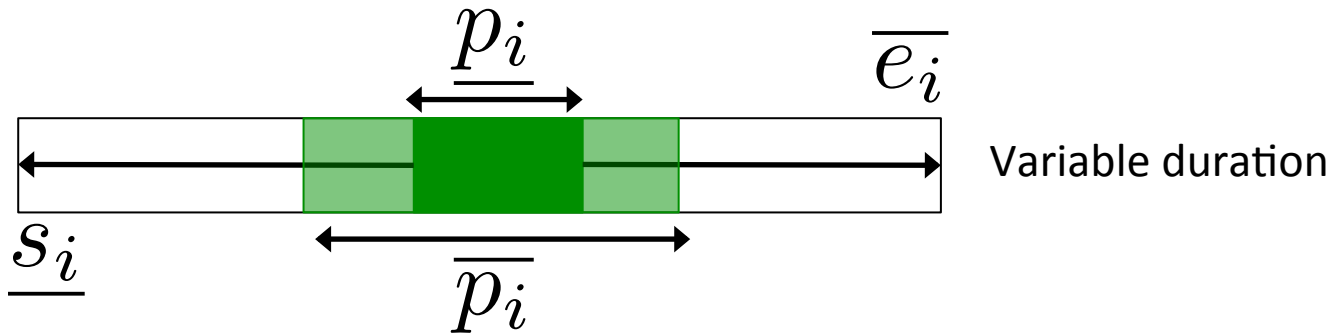
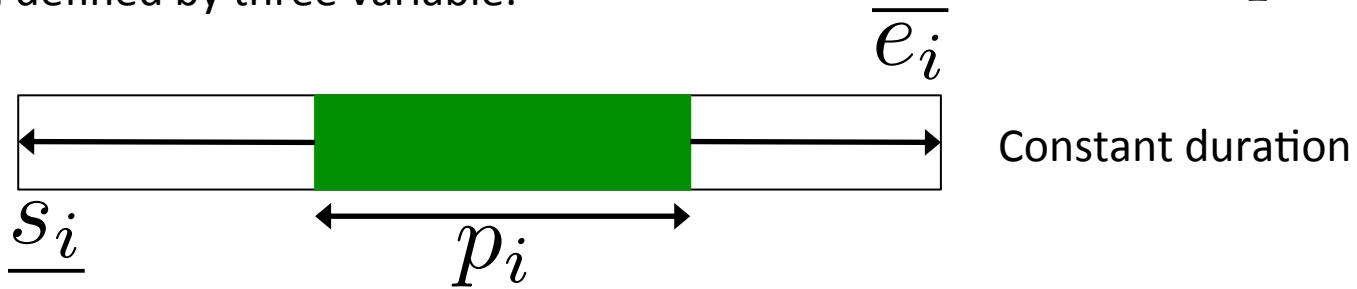
$$x_1 = 1, x_2 = 1, x_3 = 2, x_4 = 3, x_5 = 3$$

Disjunctive

DISJUNCTIVE($[s_1, \dots, s_n], [e_1, \dots, e_n], [p_1, \dots, p_n]$)

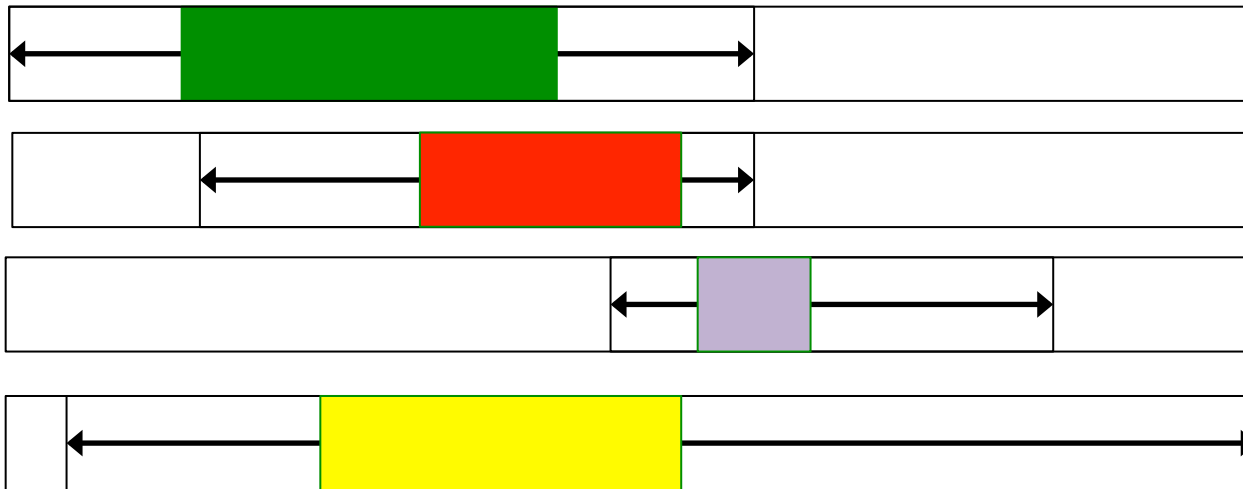
Task i defined by three variable:

$$s_i + p_i = e_i$$



Disjunctive

DISJUNCTIVE($[s_1, \dots, s_n], [e_1, \dots, e_n], [p_1, \dots, p_n]$)

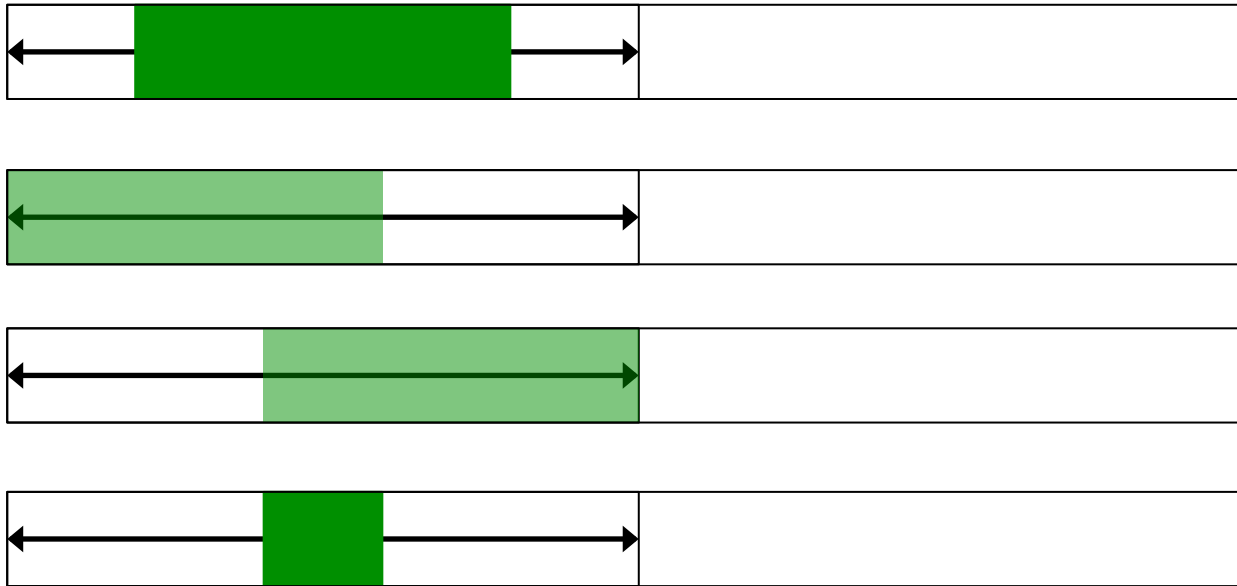


The disjunctive make sure the tasks don't overlap in time



Disjunctive

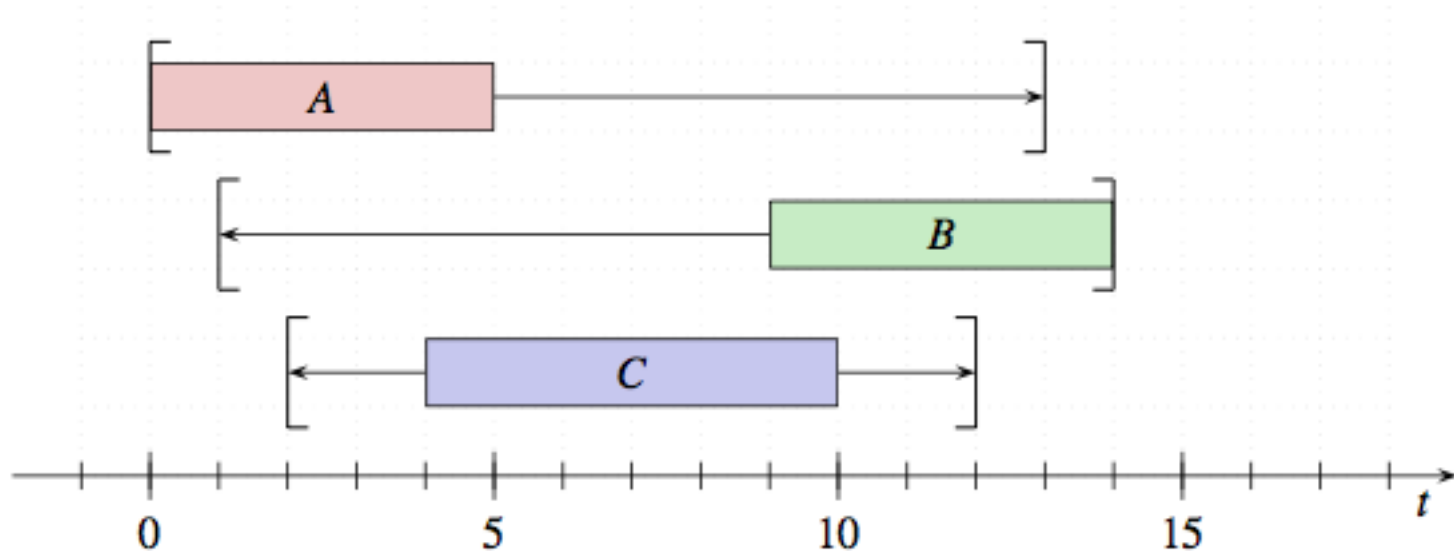
- Mandatory parts (filtering rule)



mandatory part : we can filter other tasks to make sure they will not overlap this interval

Disjunctive

- Overload checking (failure detection)

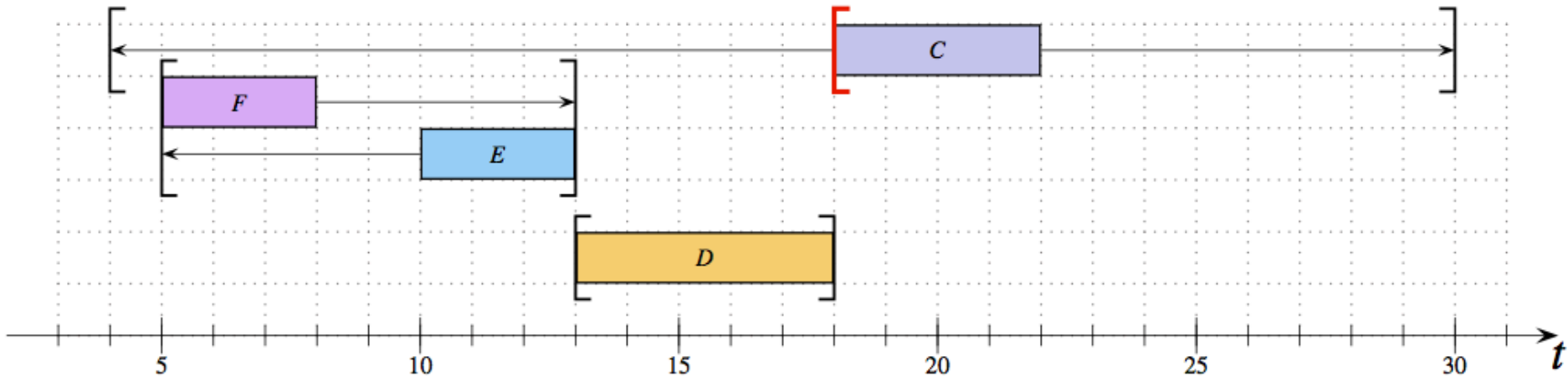


(Picture from **Petr's Villim** phd thesis)

The constraint fails (not enough space for all the three tasks)

Disjunctive

- Edge finding (filtering rule)



(Picture from **Petr's Villim** phd thesis)

The constraint infers that C should be after {F,E,D} and update the lower bound of the starting date of C.